

Chapter 1: Systems of Linear Equations and Matrices (Part 2)

1 Matrix Operations

Definition 1.1. A **matrix** is a rectangular array of numbers. The numbers in the array are called the entries in the matrix.

A general $m \times n$ matrix is of the form:

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}.$$

- A matrix \mathbf{A} with n rows and n columns is called a **square matrix** of order n .
- The entries $a_{11}, a_{22}, \dots, a_{nn}$ are said to be on the **main diagonal** of \mathbf{A} .

Definition 1.2. Two matrices are defined to be **equal** if they have the same size and their corresponding entries are equal.

Definition 1.3. Matrix Operations

- If \mathbf{A} and \mathbf{B} are matrices of the same size, then the **sum** $\mathbf{A} + \mathbf{B}$ is the matrix obtained by adding the entries of \mathbf{B} to the corresponding entries of \mathbf{A} , and the **difference** $\mathbf{A} - \mathbf{B}$ is the matrix obtained by subtracting the entries of \mathbf{B} from the corresponding entries of \mathbf{A} . Matrices of different sizes cannot be added or subtracted.
- If \mathbf{A} is any matrix and c is any scalar, then the product $c\mathbf{A}$ is the matrix obtained by multiplying each entry of the matrix \mathbf{A} by c . The matrix $c\mathbf{A}$ is said to be a **scalar multiple** of \mathbf{A} .
- If \mathbf{A} is an $m \times r$ matrix and \mathbf{B} is an $r \times n$ matrix, then the product \mathbf{AB} is the $m \times n$ matrix whose entries are determined as follows: To find the entry in row i and column j of \mathbf{AB} , single out row i from the matrix \mathbf{A} and column j from the matrix \mathbf{B} . Multiply the corresponding entries from the row and column together, and then add up the resulting products.

Definition 1.4 (Transpose). If \mathbf{A} is any $m \times n$ matrix, then the **transpose** of \mathbf{A} , denoted by \mathbf{A}^T , is defined to be the $n \times m$ matrix that results by interchanging the rows and columns of \mathbf{A} ; that is, the first column of \mathbf{A}^T is the first row of \mathbf{A} , the second column of \mathbf{A}^T is the second row of \mathbf{A} , and so forth.

$$(\mathbf{A}^T)_{ij} = \mathbf{A}_{ji}, \quad i = 1, 2, \dots, m, \quad j = 1, 2, \dots, n.$$

Definition 1.5. If \mathbf{A} is a square matrix, then the **trace** of \mathbf{A} , denoted by $tr(\mathbf{A})$, is defined to be the sum of the entries on the main diagonal of \mathbf{A} .

Note: The trace of \mathbf{A} is undefined if \mathbf{A} is not a square matrix.

Example 1.1. Find trace of the following matrices.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 1 & 2 & 4 & 0 \\ 1 & 0 & 0 & 0 \\ -1 & -2 & -1 & 10 \\ 0 & 1 & 1 & -3 \end{bmatrix}.$$

1.1 Matrix Multiplication by Columns and by Rows

We can use matrix partitioning for finding particular rows or columns of a matrix product \mathbf{AB} without computing the entire product. Specifically, the following formulas, whose proofs are left as exercises, show how individual column vectors of \mathbf{AB} can be obtained by partitioning \mathbf{B} into column vectors and how individual row vectors of \mathbf{AB} can be obtained by partitioning \mathbf{A} into row vectors.

\mathbf{AB} computed column by column

$$\mathbf{AB} = \mathbf{A}[\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n] = [\mathbf{Ab}_1, \mathbf{Ab}_2, \dots, \mathbf{Ab}_n]$$

I.e. “the j -th column vector of $\mathbf{AB} = \mathbf{A}[j\text{-th column vector of } \mathbf{B}]$ ”

\mathbf{AB} computed row by row

$$\mathbf{AB} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} \mathbf{B} = \begin{bmatrix} a_1 \mathbf{B} \\ a_2 \mathbf{B} \\ \vdots \\ a_m \mathbf{B} \end{bmatrix}.$$

I.e. “the i -th row vector of $\mathbf{AB} = [i\text{-th row vector of } \mathbf{A}]\mathbf{B}$ ”

1.1.1 Matrix Products as Linear Combinations

Definition 1.6 (Linear Combination). If $\mathbf{A}_1, \mathbf{A}_2, \dots, \mathbf{A}_r$ are matrices of the same size, and if c_1, c_2, \dots, c_r are scalars, then an expression of the form

$$c_1\mathbf{A}_1 + c_2\mathbf{A}_2 + \cdots + c_r\mathbf{A}_r$$

is called a **linear combination** of $\mathbf{A}_1, \mathbf{A}_2, \dots, \mathbf{A}_r$ with **coefficients** c_1, c_2, \dots, c_r .

Theorem 1.1. If \mathbf{A} is an $m \times n$ matrix, and if \mathbf{x} is an $n \times 1$ column vector, then the product $\mathbf{A}\mathbf{x}$ can be expressed as a linear combination of the column vectors of \mathbf{A} in which the coefficients are the entries of \mathbf{x} .

Proof:

Example 1.2. (Exercise) Consider the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 11 \\ 11 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 11 \\ 11 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 11 \\ 11 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} 121 \\ 221 \\ 1211 \\ 1111 \end{bmatrix},$$

Determine whether or not \mathbf{w} can be expressed as a linear combination $w = \lambda_1\mathbf{v}_1 + \lambda_2\mathbf{v}_2 + \lambda_3\mathbf{v}_3$ and if so, what are the relevant values λ_1, λ_2 , and λ_3 ?

Example 7.7. Consider the vectors

$$v_1 = \begin{bmatrix} 11 \\ 11 \\ 1 \\ 1 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1 \\ 11 \\ 11 \\ 1 \end{bmatrix} \quad v_3 = \begin{bmatrix} 1 \\ 1 \\ 11 \\ 11 \end{bmatrix} \quad w = \begin{bmatrix} 121 \\ 221 \\ 1211 \\ 1111 \end{bmatrix}.$$

We ask whether w can be expressed as a linear combination $w = \lambda_1 v_1 + \lambda_2 v_2 + \lambda_3 v_3$, and if so, what are the relevant values λ_1 , λ_2 and λ_3 ? Following Method 7.6, we write down the augmented matrix $[v_1|v_2|v_3|w]$ and row-reduce it:

$$\begin{aligned} & \left[\begin{array}{ccc|c} 11 & 1 & 1 & 121 \\ 11 & 11 & 1 & 221 \\ 1 & 11 & 11 & 1211 \\ 1 & 1 & 11 & 1111 \end{array} \right] \xrightarrow{1} \left[\begin{array}{ccc|c} 1 & 1 & 11 & 1111 \\ 11 & 1 & 1 & 121 \\ 11 & 11 & 1 & 221 \\ 1 & 11 & 11 & 1211 \end{array} \right] \xrightarrow{2} \\ & \left[\begin{array}{ccc|c} 1 & 1 & 11 & 1111 \\ 0 & -10 & -120 & -12100 \\ 0 & 0 & -120 & -12000 \\ 0 & 10 & 0 & 100 \end{array} \right] \xrightarrow{3} \left[\begin{array}{ccc|c} 1 & 1 & 11 & 1111 \\ 0 & 1 & 12 & 1210 \\ 0 & 0 & 1 & 100 \\ 0 & 1 & 0 & 10 \end{array} \right] \xrightarrow{4} \\ & \left[\begin{array}{ccc|c} 1 & 1 & 0 & 11 \\ 0 & 1 & 0 & 10 \\ 0 & 0 & 1 & 100 \\ 0 & 1 & 0 & 10 \end{array} \right] \xrightarrow{5} \left[\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 10 \\ 0 & 0 & 1 & 100 \\ 0 & 0 & 0 & 0 \end{array} \right] \end{aligned}$$

(1: move the bottom row to the top; 2: subtract multiples of row 1 from the other rows; 3: divide rows 2,3 and 4 by -10 , -120 and 10 ; 4: subtract multiples of row 3 from the other rows; 5: subtract multiples of row 2 from the other rows.)

The final matrix corresponds to the system of equations

$$\lambda_1 = 1 \quad \lambda_2 = 10 \quad \lambda_3 = 100 \quad 0 = 0$$

so we conclude that

$$w = v_1 + 10v_2 + 100v_3.$$

In particular, w can be expressed as a linear combination of v_1 , v_2 and v_3 . We can check the above equation directly:

$$v_1 + 10v_2 + 100v_3 = \begin{bmatrix} 11 \\ 11 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 10 \\ 110 \\ 110 \\ 10 \end{bmatrix} + \begin{bmatrix} 100 \\ 100 \\ 1100 \\ 1100 \end{bmatrix} = \begin{bmatrix} 121 \\ 221 \\ 1211 \\ 1111 \end{bmatrix} = w.$$

Example 7.8. Consider the vectors

$$a_1 = \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} \quad a_2 = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} \quad a_3 = \begin{bmatrix} 0 \\ 3 \\ -2 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

To test whether b is a linear combination of a_1 , a_2 and a_3 , we write down the relevant augmented matrix and row-reduce it:

$$\begin{aligned} \left[\begin{array}{ccc|c} 2 & 3 & 0 & 1 \\ -1 & 0 & 3 & 2 \\ 0 & -1 & -2 & 3 \end{array} \right] &\xrightarrow{1} \left[\begin{array}{ccc|c} 1 & 0 & -3 & -2 \\ 0 & 1 & 2 & -3 \\ 2 & 3 & 0 & 1 \end{array} \right] \xrightarrow{2} \\ \left[\begin{array}{ccc|c} 1 & 0 & -3 & -2 \\ 0 & 1 & 2 & -3 \\ 0 & 3 & 6 & 5 \end{array} \right] &\xrightarrow{3} \left[\begin{array}{ccc|c} 1 & 0 & -3 & -2 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & 0 & 14 \end{array} \right] \xrightarrow{4} \\ \left[\begin{array}{ccc|c} 1 & 0 & -3 & -2 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & 0 & 1 \end{array} \right] &\xrightarrow{5} \left[\begin{array}{ccc|c} 1 & 0 & -3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] \end{aligned}$$

(Stage 1: move the top row to the bottom, and multiply the other two rows by -1 ; Stage 2: subtract 2 times row 1 from row 3; Stage 3: subtract 3 times row 2 from row 3; Stage 4: divide row 3 by 14; Stage 5: subtract multiples of row 3 from rows 1 and 2.)

1.1.2 Linear independence

Definition 1.7. Let $\mathcal{V} = \mathbf{v}_1, \dots, \mathbf{v}_k$ be a list of vectors in \mathbb{R}^n .

Suppose that there is a linear relation between the vectors \mathbf{v}_i is a relation of the form

$$\lambda_1 \mathbf{v}_1 + \dots + \lambda_k \mathbf{v}_k = 0$$

where $\lambda_1, \dots, \lambda_k$ are scalars. In other words, we can express 0 as a linear combination of \mathcal{V} .

- For any list we have the **trivial** linear relation

$$0v_1 + 0v_2 + \dots + 0v_k = 0.$$

- There may or may not be any **nontrivial** linear relations.
- If the list \mathcal{V} has a **nontrivial** linear relation, we say that it is a **linearly dependent** list.
- If the only linear relation on \mathcal{V} is the **trivial one**, we instead say that \mathcal{V} is **linearly independent** or just **independent**.

Example 1.3. Consider the list \mathcal{V} given by

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \quad v_4 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}.$$

Determine if the list \mathcal{V} is linearly dependent.

Solution: Since there is a nontrivial linear relation $\mathbf{v}_1 + \mathbf{v}_2 - \mathbf{v}_3 - \mathbf{v}_4 = 0$, then the list \mathcal{A} is dependent.

Example 1.4. Consider the list \mathcal{A} given by

$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \mathbf{a}_2 = \begin{bmatrix} 12 \\ 1 \end{bmatrix}, \quad \mathbf{a}_3 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}, \quad \mathbf{a}_4 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

Determine if there is a nontrivial linear relation on the list \mathcal{A} .

Solution: Since there is a nontrivial linear relation $3\mathbf{a}_1 + \mathbf{a}_2 + 3\mathbf{a}_3 - 4\mathbf{a}_4 = 0$, then the list \mathcal{A} is dependent.

Example 1.5. Consider the list \mathcal{U} given by

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}.$$

Determine if the list \mathcal{U} is linearly dependent.

Example 1.6. Let \mathbf{v} and \mathbf{w} be vectors in \mathbb{R}^n , and suppose that $\mathbf{v} \neq \mathbf{0}$ and that the list (\mathbf{v}, \mathbf{w}) is linearly dependent.

Prove that there is a number α such that $\mathbf{w} = \alpha\mathbf{v}$.

Proof

Because the list is dependent, there is a linear relation

$$\lambda\mathbf{v} + \mu\mathbf{w} = \mathbf{0}$$

where λ and μ are not both zero.

There are apparently three possibilities:

- (a) $\lambda \neq 0$ and $\mu \neq 0$;
- (b) $\lambda = 0$ and $\mu \neq 0$;
- (c) $\lambda \neq 0$ and $\mu = 0$;

However, case (c) is not really possible. Indeed, in case (c) the equation $\lambda\mathbf{v} + \mu\mathbf{w} = \mathbf{0}$ would reduce to $\lambda\mathbf{v} = \mathbf{0}$, and we could multiply by $1/\lambda$ to get $\mathbf{v} = \mathbf{0}$, which contradicts that $\mathbf{v} \neq \mathbf{0}$ by assumption.

In case (a) or (b) we can take $\alpha = -\lambda/\mu$ and we have $\mathbf{w} = \alpha\mathbf{v}$.

1.1.3 Checking linear dependence by using row-reduction

There is a systematic method using row-reduction for checking linear (in)dependence, as we will explain shortly. We first need a preparatory observation

We will consider 3 case of matrix \mathbf{B} of size $p \times q$.

- When $p < q$, the matrix \mathbf{B} is said to be “*wide*.”
- When $p = q$, the matrix \mathbf{B} is said to be “*square*.”
- When $p > q$, the matrix \mathbf{B} is said to be “*tall*.”

Lemma 1.1. Let \mathbf{B} be a $p \times q$ matrix in RREF.

- (a) If \mathbf{B} is wide ($p < q$) then it is impossible for every column to contain a pivot.
- (b) If \mathbf{B} is square ($p = q$) then the only way for every column to contain a pivot is when $\mathbf{B} = \mathbf{I}_q$.
- (c) If \mathbf{B} is tall ($p > q$) then the only way for every column to contain a pivot is if \mathbf{B} consists of

\mathbf{I}_q with $p - q$ rows of zeros added at the bottom. I.e. $\mathbf{B} = \begin{bmatrix} \mathbf{I}_q \\ \mathbf{0}_{(p-q) \times q} \end{bmatrix}$

Proof:

Theorem 1.2. Procedure for checking linear dependence by using row-reduction

Let $\mathcal{V} = \mathbf{v}_1, \dots, \mathbf{v}_K$ be a list of vectors in \mathbb{R}^n . We can check whether this list is dependent as follows. Let

$$\mathbf{A} = \left[\begin{array}{c|c|c|c} \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_K \end{array} \right]$$

and let \mathbf{B} be the RREF of \mathbf{A} . Then

- If every column of \mathbf{B} contains a pivot (so \mathbf{B} has the form discussed in the previous Lemma) then \mathcal{V} is independent.
- If some column of \mathbf{B} has no pivot, then the list \mathcal{V} is dependent. Moreover, we can find the coefficients λ_i in a nontrivial linear relation by solving the vector equation $\mathbf{B}\lambda = 0$ (which is easy because \mathbf{B} is in RREF).

Proof:

Proof of correctness of Method 8.8. Put

$$A = \left[\begin{array}{c|c|c} v_1 & \cdots & v_m \end{array} \right]$$

as in step (a) of the method, and let B be the RREF form of A . Note that for any vector $\lambda = [\lambda_1 \ \dots \ \lambda_m]^T \in \mathbb{R}^m$, we have

$$A\lambda = \left[\begin{array}{c|c|c} v_1 & \cdots & v_m \end{array} \right] \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{bmatrix} = \lambda_1 v_1 + \cdots + \lambda_m v_m.$$

Thus, linear relations on our list are just the same as solutions to the homogeneous equation $A\lambda = 0$. By Theorem 6.8, these are the same as solutions to the equation $B\lambda = 0$, which can be found by Method 5.4. If there is a pivot in every column then none of the variables λ_i is independent, so the only solution is $\lambda_1 = \lambda_2 = \cdots = \lambda_m = 0$. Thus, the only linear relation on \mathcal{V} is the trivial one, which means that the list \mathcal{V} is linearly independent.

Suppose instead that some column (the k 'th one, say) does not contain a pivot. Then in Method 5.4 the variable λ_k will be independent, so we can choose $\lambda_k = 1$. This will give us a nonzero solution to $B\lambda = 0$, or equivalently $A\lambda = 0$, corresponding to a nontrivial linear relation on \mathcal{V} . This shows that \mathcal{V} is linearly dependent. \square

Remarks

If $K \geq n$ then \mathcal{V} is automatically dependent and we do not need to go through the method.

For example, any list of 5 vectors in \mathbb{R}^3 is automatically dependent, any list of 10 vectors in \mathbb{R}^9 is automatically dependent, and so on.)

Indeed, in this case the matrices \mathbf{A} and \mathbf{B} are wide, so it is impossible for \mathbf{B} to have a pivot in every column.

Example 1.7. Consider the list \mathcal{V} given by

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \quad v_4 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}.$$

Determine if the list \mathcal{V} is linearly dependent.

Solution:

Example 8.10. In example 8.2 we considered the list

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \quad v_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad v_4 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}.$$

We can write down the corresponding matrix and row-reduce it as follows:

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \xrightarrow{1} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \xrightarrow{2} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \xrightarrow{3} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The end result has no pivot in the last column, so the original list is dependent. To find a specific linear relation, we solve the equation

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

to get $\lambda_1 = -\lambda_4$, $\lambda_2 = -\lambda_4$ and $\lambda_3 = \lambda_4$ with λ_4 arbitrary. Taking $\lambda_4 = 1$ gives $(\lambda_1, \lambda_2, \lambda_3, \lambda_4) = (-1, -1, 1, 1)$, corresponding to the relation $-v_1 - v_2 + v_3 + v_4 = 0$.

Example 1.8. Consider the list \mathcal{A} given by

$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \mathbf{a}_2 = \begin{bmatrix} 12 \\ 1 \end{bmatrix}, \quad \mathbf{a}_3 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}, \quad \mathbf{a}_4 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

Determine if there is a nontrivial linear relation on the list \mathcal{A} .

Solution:

Example 8.11. In Example 8.3 we considered the list

$$a_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad a_2 = \begin{bmatrix} 12 \\ 1 \end{bmatrix} \quad a_3 = \begin{bmatrix} -1 \\ -1 \end{bmatrix} \quad a_4 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

Here we have 4 vectors in \mathbb{R}^2 , so they must be dependent by Remark 8.9. Thus, there exist nontrivial linear relations

$$\lambda_1 a_1 + \lambda_2 a_2 + \lambda_3 a_3 + \lambda_4 a_4 = 0.$$

To actually find such a relation, we write down the corresponding matrix and row-reduce it as follows:

$$\begin{bmatrix} 1 & 12 & -1 & 3 \\ 2 & 1 & -1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 12 & -1 & 3 \\ 0 & -23 & 1 & -5 \end{bmatrix} \rightarrow$$

$$\begin{bmatrix} 1 & 12 & -1 & 3 \\ 0 & 1 & -1/23 & 5/23 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -11/23 & 9/23 \\ 0 & 1 & -1/23 & 5/23 \end{bmatrix}$$

We now need to solve the matrix equation

$$\begin{bmatrix} 1 & 0 & -11/23 & 9/23 \\ 0 & 1 & -1/23 & 5/23 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

As this is in RREF, we can just read off the solution: $\lambda_1 = \frac{11}{23}\lambda_3 - \frac{9}{23}\lambda_4$ and $\lambda_2 = \frac{1}{23}\lambda_3 - \frac{5}{23}\lambda_4$ with λ_3 and λ_4 arbitrary. If we choose $\lambda_3 = 23$ and $\lambda_4 = 0$ we get $(\lambda_1, \lambda_2, \lambda_3, \lambda_4) = (11, 1, 23, 0)$ so we have a relation

$$11a_1 + a_2 + 23a_3 + 0a_4 = 0.$$

(You should check directly that this is correct.) Alternatively, we can choose $\lambda_3 = 3$ and $\lambda_4 = -4$. Using the equations $\lambda_1 = \frac{11}{23}\lambda_3 - \frac{9}{23}\lambda_4$ and $\lambda_2 = \frac{1}{23}\lambda_3 - \frac{5}{23}\lambda_4$ we get $\lambda_1 = 3$ and $\lambda_2 = 1$ giving a different relation

$$3a_1 + a_2 + 3a_3 - 4a_4 = 0.$$

This is the relation that we observed in Example 8.3.

Example 1.9. Consider the list \mathcal{U} given by

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}.$$

Determine if the list \mathcal{U} is linearly dependent.

Example 8.12. In Example 8.4 we considered the list \mathcal{U} given by

$$u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad u_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} \quad u_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}.$$

We can write down the corresponding matrix and row-reduce it as follows:

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ \hline 0 & 0 & 0 \end{bmatrix}$$

The final matrix has a pivot in every column, as in Lemma 8.7. It follows that the list \mathcal{U} is independent.

2 Algebraic Properties of Matrices

Theorem 2.1. Properties of Matrix Arithmetic

Assuming that the sizes of the matrices are such that the indicated operations can be performed, the following rules of matrix arithmetic are valid.

- (a) $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$ [Commutative law for matrix addition]
- (b) $\mathbf{A} + (\mathbf{B} + \mathbf{C}) = (\mathbf{A} + \mathbf{B}) + \mathbf{C}$ [Associative law for matrix addition]
- (c) $\mathbf{A}(\mathbf{BC}) = (\mathbf{AB})\mathbf{C}$ [Associative law for matrix multiplication]
- (d) $\mathbf{A}(\mathbf{B} + \mathbf{C}) = \mathbf{AB} + \mathbf{AC}$ [Left distributive law]
- (e) $(\mathbf{B} + \mathbf{C})\mathbf{A} = \mathbf{BA} + \mathbf{CA}$ [Right distributive law]
- (f) $\mathbf{A}(\mathbf{B} - \mathbf{C}) = \mathbf{AB} - \mathbf{AC}$
- (g) $(\mathbf{B} - \mathbf{C})\mathbf{A} = \mathbf{BA} - \mathbf{CA}$
- (h) $a(\mathbf{B} + \mathbf{C}) = a\mathbf{B} + a\mathbf{C}$
- (i) $a(\mathbf{B} - \mathbf{C}) = a\mathbf{B} - a\mathbf{C}$
- (j) $(a + b)\mathbf{C} = a\mathbf{C} + b\mathbf{C}$
- (k) $(a - b)\mathbf{C} = a\mathbf{C} - b\mathbf{C}$
- (l) $a(b\mathbf{C}) = (ab)\mathbf{C}$
- (m) $a(\mathbf{BC}) = (a\mathbf{B})\mathbf{C} = \mathbf{B}(a\mathbf{C})$

Proof of (d)

Proof (d) We must show that $A(\mathbf{B} + \mathbf{C})$ and $\mathbf{AB} + \mathbf{AC}$ have the same size and that corresponding entries are equal. To form $A(\mathbf{B} + \mathbf{C})$, the matrices \mathbf{B} and \mathbf{C} must have the same size, say $m \times n$, and the matrix A must then have m columns, so its size must be of the form $r \times m$. This makes $A(\mathbf{B} + \mathbf{C})$ an $r \times n$ matrix. It follows that $\mathbf{AB} + \mathbf{AC}$ is also an $r \times n$ matrix and, consequently, $A(\mathbf{B} + \mathbf{C})$ and $\mathbf{AB} + \mathbf{AC}$ have the same size.

Suppose that $A = [a_{ij}]$, $\mathbf{B} = [b_{ij}]$, and $\mathbf{C} = [c_{ij}]$. We want to show that corresponding entries of $A(\mathbf{B} + \mathbf{C})$ and $\mathbf{AB} + \mathbf{AC}$ are equal; that is,

$$(A(\mathbf{B} + \mathbf{C}))_{ij} = (\mathbf{AB} + \mathbf{AC})_{ij}$$

for all values of i and j . But from the definitions of matrix addition and matrix multiplication, we have

$$\begin{aligned} (A(\mathbf{B} + \mathbf{C}))_{ij} &= a_{i1}(b_{1j} + c_{1j}) + a_{i2}(b_{2j} + c_{2j}) + \cdots + a_{im}(b_{mj} + c_{mj}) \\ &= (a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{im}b_{mj}) + (a_{i1}c_{1j} + a_{i2}c_{2j} + \cdots + a_{im}c_{mj}) \\ &= (\mathbf{AB})_{ij} + (\mathbf{AC})_{ij} = (\mathbf{AB} + \mathbf{AC})_{ij} \quad \blacktriangleleft \end{aligned}$$

Remarks

It is not true that all laws of real arithmetic carry over to matrix arithmetic.

1. No commutative law:

For example, in real arithmetic it is always true that $ab = ba$, which is called the commutative law for multiplication. In matrix arithmetic, however, the equality of \mathbf{AB} and \mathbf{BA} can fail for three possible reasons:

- \mathbf{AB} may be defined and \mathbf{BA} may not (for example, if \mathbf{A} is 2×3 and \mathbf{B} is 3×4).
- \mathbf{AB} and \mathbf{BA} may both be defined, but they may have different sizes (for example, if \mathbf{A} is 2×3 and \mathbf{B} is 3×2).
- \mathbf{AB} and \mathbf{BA} may both be defined and have the same size, but the two products may be different (as illustrated in the next example).

2. No cancellation law:

$$\mathbf{AB} = \mathbf{AC} \quad \not\Rightarrow \quad \mathbf{B} = \mathbf{C}$$

Example:

3. A Zero Product with Nonzero Factors

$$\mathbf{AB} = \mathbf{0} \quad \not\Rightarrow \quad \mathbf{A} = \mathbf{0} \quad \text{and} \quad \mathbf{B} = \mathbf{0}$$

Example:

▶ EXAMPLE 3 Failure of the Cancellation Law

Consider the matrices

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 1 \\ 3 & 4 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 5 \\ 3 & 4 \end{bmatrix}$$

We leave it for you to confirm that

$$AB = AC = \begin{bmatrix} 3 & 4 \\ 6 & 8 \end{bmatrix}$$

Although $A \neq 0$, canceling A from both sides of the equation $AB = AC$ would lead to the incorrect conclusion that $B = C$. Thus, the cancellation law does not hold, in general, for matrix multiplication (though there may be particular cases where it is true).

▶ EXAMPLE 4 A Zero Product with Nonzero Factors

Here are two matrices for which $AB = 0$, but $A \neq 0$ and $B \neq 0$:

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 7 \\ 0 & 0 \end{bmatrix} \quad \blacktriangleleft$$

3 Inverse of Matrix

Definition 3.1. Let \mathbf{A} be a square matrix.

- If a matrix \mathbf{B} of the same size can be found such that $\mathbf{AB} = \mathbf{BA} = \mathbf{I}$, then \mathbf{A} is said to be **invertible** (or **nonsingular**) and \mathbf{B} is called an **inverse** of \mathbf{A} .
Note: In this case, we also have that \mathbf{B} is **invertible** (or **nonsingular**) and \mathbf{A} is called an **inverse** of \mathbf{B} .
- If no such matrix \mathbf{B} can be found, then \mathbf{A} is said to be **singular**.

Example 3.1.

$$\mathbf{A} = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}.$$

$$\mathbf{AB} = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

$$\mathbf{BA} = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Thus, \mathbf{A} and \mathbf{B} are invertible and each is an inverse of the other.

Theorem 3.1 (Uniqueness of inverse). An invertible matrix has exactly one inverse. I.e. If \mathbf{B} and \mathbf{C} are both inverses of the matrix \mathbf{A} , then $\mathbf{B} = \mathbf{C}$.

THEOREM 1.4.4 *If B and C are both inverses of the matrix A , then $B = C$.*

Proof Since B is an inverse of A , we have $BA = I$. Multiplying both sides on the right by C gives $(BA)C = IC = C$. But it is also true that $(BA)C = B(AC) = BI = B$, so $C = B$. ◀

If $\mathbf{A} \in \mathbb{R}^{n \times n}$ is invertible, then its inverse will be denoted by the symbol \mathbf{A}^{-1} . I.e.

$$\mathbf{AA}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I}_n$$

3.1 Computing the inverse of an invertible matrix

Theorem 3.2. The matrix $\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible if and only if $ad - bc \neq 0$, in which case the inverse is given by the formula

$$\mathbf{A}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$$

Example 3.2. Determine whether each of the following matrices is invertible. If so, find its inverse.

$$(a) \begin{bmatrix} 6 & 1 \\ 5 & 2 \end{bmatrix} \quad \begin{bmatrix} -1 & 2 \\ 3 & -6 \end{bmatrix}$$

Example 3.3. Solve a pair of equations of the form

$$\begin{aligned} u &= ax + by \\ v &= cx + dy \end{aligned}$$

for x and y in terms of a, b, c, d, u and v .

Theorem 3.3. If \mathbf{A} and \mathbf{B} are invertible matrices with the same size, then \mathbf{AB} is invertible and

$$(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$$

A product of any number of invertible matrices is invertible, and the inverse of the product is the product of the inverses in the reverse order.

Proof:

THEOREM 1.4.6 *If A and B are invertible matrices with the same size, then AB is invertible and*

$$(AB)^{-1} = B^{-1}A^{-1}$$

Proof We can establish the invertibility and obtain the stated formula at the same time by showing that

$$(AB)(B^{-1}A^{-1}) = (B^{-1}A^{-1})(AB) = I$$

But

$$(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I$$

and similarly, $(B^{-1}A^{-1})(AB) = I$. ◀

Example 3.4. Show that $(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$.

Consider the matrices

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 2 \\ 2 & 2 \end{bmatrix}$$

We leave it for you to show that

$$AB = \begin{bmatrix} 7 & 6 \\ 9 & 8 \end{bmatrix}, \quad (AB)^{-1} = \begin{bmatrix} 4 & -3 \\ -\frac{9}{2} & \frac{7}{2} \end{bmatrix}$$

and also that

$$A^{-1} = \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix}, \quad B^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & \frac{3}{2} \end{bmatrix}, \quad B^{-1}A^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & \frac{3}{2} \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & -3 \\ -\frac{9}{2} & \frac{7}{2} \end{bmatrix}$$

Powers of a Matrix

Let \mathbf{A} be a square matrix.

- We define the nonnegative integer powers of \mathbf{A} to be

$$\mathbf{A}^0 = \mathbf{I} \quad \text{and} \quad \mathbf{A}^n = \mathbf{A}\mathbf{A}\dots\mathbf{A} \quad [\text{n factors}]$$

- If \mathbf{A} is invertible, then we define the negative integer powers of \mathbf{A} to be

$$\mathbf{A}^{-n} = (\mathbf{A}^{-1})^n = \mathbf{A}^{-1}\mathbf{A}^{-1}\dots\mathbf{A}^{-1} \quad [\text{n factors}]$$

-

$$\mathbf{A}^r \mathbf{A}^s = \mathbf{A}^{r+s}$$

$$(\mathbf{A}^r)^s = \mathbf{A}^{rs}$$

Example 3.5. Let $\mathbf{A}^{-3} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Find \mathbf{A}^6 .

Example 3.6. Prove that if \mathbf{A} is an invertible matrix, then A^T is also invertible and

$$(\mathbf{A}^T)^{-1} = (\mathbf{A}^{-1})^T.$$

Proof We can establish the invertibility and obtain the formula at the same time by showing that

$$A^T(A^{-1})^T = (A^{-1})^T A^T = I$$

But from part (e) of Theorem 1.4.8 and the fact that $I^T = I$, we have

$$A^T(A^{-1})^T = (A^{-1}A)^T = I^T = I$$

$$(A^{-1})^T A^T = (AA^{-1})^T = I^T = I$$

which completes the proof. ◀