

3 Remedial measures

As mentioned before, there are 2 types of remedies – passive and active.

- The passive remedies just re-calculate the *std.err.* or $\hat{\beta}$ using the heteroskedasticity-robust standard error formula(s).
- The active remedies include the "weighted least squares (WLS) estimators", "generalized least squares (GLS) estimators", or "feasible GLS estimator".

3.1 Weighted Least Squares (WLS)

We assume that the heteroskedasticity may take the pattern

From

$$\begin{aligned} \text{Var}(u_i|\mathbf{x}) &= E(u_i^2|\mathbf{x}) - [E(u_i|\mathbf{x})]^2 \\ &= \end{aligned}$$

We get

To make the error term become homoskedastic, we weight every term by $\sqrt{h_i}$.

How do we find h_i or $\sqrt{h_i}$, the heteroskedasticity function?

1. If the heteroskedasticity is "known" to be caused by a multiplicative constant, we can adjust using that constant.
2. If the heteroskedasticity pattern is not known, we can estimate it. This procedure is called "Feasible Generalized Least Squares" (also called Feasible GLS or FGLS)

3.2 Feasible GLS

Since $Var(\hat{\beta}_j)$ would not be unbiased, we can make valid inferences about β_j , e.g. can use t-test, F-test, etc.

Feasible GLS in practice

1. Get $\hat{\beta}_1, \hat{\beta}_2, \dots, \hat{\beta}_k$ by OLS. (regress y x_1 x_2 ... x_k)
2. Calculate $\hat{u}_i = [y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_1 + \hat{\beta}_2 x_2 + \hat{\beta}_k x_k)]$ (predict u_hat , residual)
3. Create $\log(\hat{u}_i^2)$ (generate $\log_u_sq = \log(u_hat^2)$)
4. Estimate $\log(\hat{u}_i^2) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_k x_k + error$ (regress $\log_u_sq$ x_1 x_2 ... x_k)
5. Obtain the fitted value of $\widehat{\log(\hat{u}_i^2)}$, called $\hat{g}$. (predict g_hat , xb)
6. Create $\hat{h} = \exp(\hat{g})$ (generate $h_hat = \exp(g_hat)$)
7. Divide y and each x_{ij} by $\hat{h}$
8. Estimate $\frac{y}{\sqrt{\hat{h}}} = \frac{\lambda_0}{\sqrt{\hat{h}}} + \lambda_1 \frac{x_1}{\sqrt{\hat{h}}} + \lambda_2 \frac{x_2}{\sqrt{\hat{h}}} + \dots + \lambda_k \frac{x_k}{\sqrt{\hat{h}}} + \frac{error}{\sqrt{\hat{h}}}$

Steps 7 & 8 on STATA would be: regress y x_1 x_2 ... x_k [aweight = $\frac{1}{\sqrt{\hat{h}}}$]

3.3 What if the assumed h_i function is wrong?

More on Specification and Data Issues

- Heteroskedasticity problem - not serious
- Specification error problem -serious!

1 Functional Form Misspecification

Suppose the true model is

$$\log(wage) = \beta_0 + \beta_1 educ + \beta_2 \exp er + \beta_3 \exp er^2 + u.$$

- But we do not include $\exp er^2$, and estimate

$$\log(wage) = \beta_0 + \beta_1 educ + \beta_2 \exp er + u.$$

- Our $\beta_0, \beta_1, \beta_2$ could be biased.
- The severity of biasedness depends on

1.1 The RESET test

Rationale behind – add polynomial terms ($x^2, x^3, \dots$) to the model and test whether the coefficients are significant. If significant, then we need to include non-linear terms.

Suppose we have a linear baseline model to begin with

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + u \tag{11.1}$$

To save the # of regressors (save d.f.), we can instead estimate

1.2 Tests against Nonnested Alternatives

For example, to test

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + u \quad (\text{Model \#1})$$

against

$$y = \beta_0 + \beta_1 \log(x_1) + \beta_2 \log(x_2) + u. \quad (\text{Model \#2})$$

Which one should we use? There are many methods which can help us justify:

1. Use the RESET test

2. Mizon and Richard (1986)

3. Davidson-MacKinnon Test

Rationale - If Model#1 is true, then the fitted values ($\hat{y}$) from Model#2 should not be significant!

2 Using Proxy Variables for Unobserved Explanatory Variables

In many cases, we cannot observe some important variables

$$\log(wage) = \beta_0 + \beta_1 educ + \beta_2 exp\ er + \beta_3 ability + u.$$

- Ability is unobserved, but is very likely to explain wage or $\log(wage)$.
- Ability is very likely to be correlated with $educ$ and $exp\ er$. If ability is omitted, $\hat{\beta}_1$ and $\hat{\beta}_2$ will be biased.

Remedy (use proxy variables (this chapter) or use instrumental variable method (not in this chapter))

2.1 Using Proxy variables

2.2 Using Lagged Dependent Variables as Proxy Variables

3 OLS with Measurement Error

Suppose

$$GDP = \beta_0 + \beta_1 exp\ ort + \beta_2 invest\ ment + \beta_3 inf\ lation + \beta_4 educ + \dots + u$$

- How do you know if a country's GDP is correctly measured?

- What about the measurement of other variables?

3.1 Measurement Error in the Dependent Variable

If there is a measurement error in y variable (dependent variable), then

3.2 Measurement Error in the Explanatory Variable

Suppose the true model is

$$y = \beta_0 + \beta_1 x_1^* + u.$$

4 Missing Data, Nonrandom Samples, Outlying Observations

4.1 *Missing Data*

Household id.	head_educ	total_income	members
1	12	12,000	2
2	14	25,000	3
3	.	60,000	2
4	4	.	4
5	8	120,000	4
6	16	32,900	2

- STATA would drop the observation with missing data. So, household 3 and 4 would not be used in the regression.
- If the missing data are missing at random, then $\hat{\beta}_{OLS}$ would not be biased.

4.2 *Nonrandom Samples*

4.3 *Outliers and Influential Observations*

5 Models with Random Slopes

- What if the partial effects of a variable depends on unobserved factors that "vary" by population unit?

$$y_i = a_i + b_i x_i$$

- This is called a random coefficient model, or a random slope model (u_i would then be absorbed into a_i).
- a_i, b_i are viewed as a random draw from the population along with the observed data.
- In any case, we cannot estimate the actual a_i, b_i (for each population unit). We can only find their average (average partial effect, APE).

$$\beta_0 = E(a_i) \quad \text{and} \quad \beta_1 = E(b_i).$$