

Last time.

2.1 First-order Linear DE

2.1.1 constant coefficient and constant term

$$y'(ct) + a y(ct) = b \quad - (4)$$

$$y(ct) = y_c + y_p$$

$$\checkmark\checkmark \boxed{y(ct) = A e^{-at} + \frac{b}{a} \quad a \neq 0}$$

$$y(ct) = \left[y(0) - \frac{b}{a} \right] e^{-at} + \frac{b}{a} \quad a \neq 0$$

$$a = 0$$

we set $y_p = k \rightarrow y'(ct) = 0$

sub into (4) $0 + 0(k) = b$

not verified $0 = b$

$$y_p = k \cdot t \rightarrow y'(ct) = k$$

sub. into (4) $k + 0(k \cdot t) = b$

$$k = b$$

$$\therefore y_p = bt$$

$$y(t) = A e^{-at} + bt$$

$$y(t) = A e^0 + bt$$

Gen. Solⁿ

$$y(t) = A + bt$$

$$a = 0$$

Def. Solⁿ

$$y(t) = y(0) + bt$$

$$a = 0$$

2.1.2. Dynamics of Mkt Price

$$P^* = \frac{\alpha + \delta}{\beta + \delta} \quad - (10)$$

$$\frac{dP}{dt} = j (Q_d - Q_s) \quad ; \quad j > 0 \quad - (11)$$

$$\frac{dP}{dt} = 0 \quad \Leftrightarrow \quad Q_d = Q_s \quad P^*$$

Equilibrium Price (P^*)

1) The mkt-clearing price \Rightarrow Price that equates Q_d and Q_s

2) The intertemporal sense ; P^* is constant overtime

sub $Q_d, Q_s \Rightarrow$ into (11)

$$\frac{dP}{dt} = j \left[\overbrace{(\alpha - \beta P)}^{Q_d} - \overbrace{(-\gamma + \delta P)}^{Q_s} \right]$$

$$\frac{dP}{dt} = j(\alpha + \gamma) - j(\beta + \delta)P$$

$$\frac{dP}{dt} + j(\beta + \delta)P = j(\alpha + \gamma)$$

$$\frac{dy}{dt} + a y(t) = b \Rightarrow$$

$$P(t) = \left[P(0) - \frac{j(\alpha + \gamma)}{j(\beta + \delta)} \right] e^{-j(\beta + \delta)t} + \frac{j(\alpha + \gamma)}{j(\beta + \delta)}$$

$$P(t) = \left[P(0) - \frac{(\alpha + \gamma)}{(\beta + \delta)} \right] e^{-j(\beta + \delta)t} + \frac{(\alpha + \gamma)}{(\beta + \delta)}$$

$$P(t) = \left[P(0) - P^* \right] e^{-kt} + P^* ; k = j(\beta + \delta)$$

— (11)'

$$k = j(\beta + \delta) > 0$$

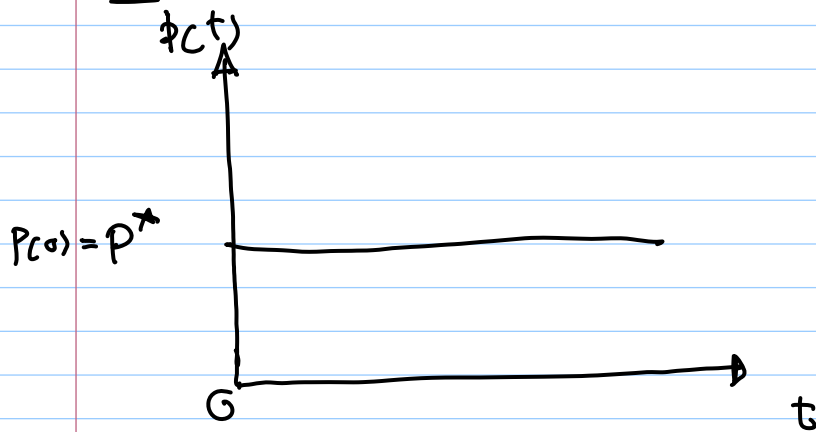
$$t \rightarrow \infty \Rightarrow e^{-kt} \rightarrow 0$$

$$\Rightarrow P(t) \rightarrow P^*$$

$P(t)$ converges to the equilibrium level P^*

P^* is Dynamically stable

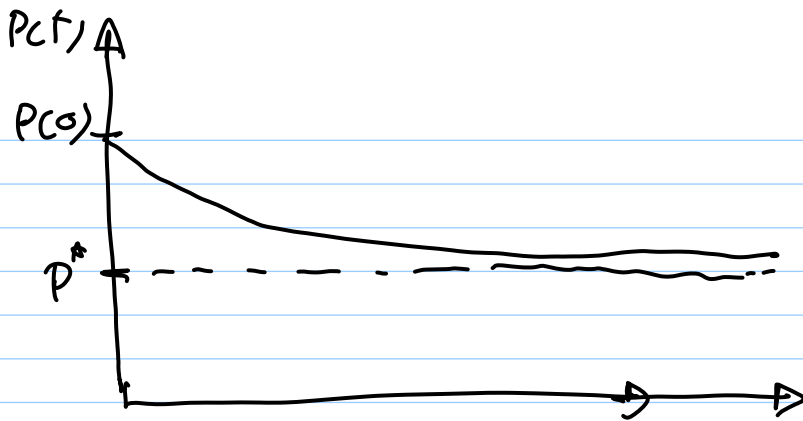
Case 1 : $P(0) = P^*$



$$P(t) = [P(0) - P^*] e^{-bt} + P^*$$

$$P(t) = P^*$$

Case 2 $P(0) > P^*$



Case 3 $P(0) < P^*$



$$\begin{aligned}
 y(t) &= y_c + y_p \\
 &= \left[y(0) - \frac{b}{a} \right] e^{-at} + \frac{b}{a}
 \end{aligned}$$

y_p = the intertemporal equilibrium of $y(t)$

y_c = the deviation from equilibrium

2.1.3 Variable coefficient and variable term

$$\frac{dy}{dt} + u(t) \cdot y(t) = w(t) \quad - (12)$$

$u(t), w(t)$ = continuous fⁿ of t

@ Homogeneous Case

$$w(t) = 0$$

$$\frac{dy(t)}{dt} + u(t) \cdot y(t) = 0 \quad - (13)$$

$$\frac{1}{y} \frac{dy}{dt} = -u(t)$$

$$\int \frac{1}{y} \frac{dy}{dt} dt = \int -u(t) dt$$

$$\ln|y| + C = - \int u(t) dt$$

$$\ln|y| = -C - \int u(t) dt$$

$$e^{\ln|y|} = e^{-c} e^{-\int u(t) dt}$$

$$y(t) = A e^{-\int u(t) dt}; A = e^{-c}$$

— (14)

(14) is the general solⁿ of (13)

Ex

$$y'(t) + 3t^2 y(t) = 0$$

$$u(t) = 3t^2$$

$$\int u(t) dt = \int 3t^2 dt$$
$$= t^3 + C$$

$$y(t) = A e^{-\int u(t) dt}$$

$$= A e^{-(t^3 + C)}$$

$$= A e^{-c} e^{-t^3}$$

$$\boxed{y(t) = B e^{-t^3}}; B = A e^{-c}$$

Check

$$y'(t) = -3t^2 B e^{-t^3}$$

sub into the original DE

$$-3t^2 B e^{-t^3} + (3t^2) (B e^{-t^3}) = 0$$

$$\overbrace{y'(t)}$$

$$\overbrace{y(t)}$$

$$0 = 0$$

The Nonhomogeneous Case

$$w(t) \neq 0$$

$$y(t) = e^{-\int u(t) dt} \left[A + \int w(t) e^{\int u(t) dt} dt \right]$$

— (15)

To get (15), we use the concept of EXACT DE

2.1.4 Exact Differential Equations

consider

$$g(y, t) \cdot \frac{dy}{dt} + f(y, t) = 0 \quad - (16)$$

suppose we have a f^2 $F(y, t)$ such that

$$\frac{\partial F(y, t)}{\partial t} = f(y, t)$$

$$\frac{\partial F(y, t)}{\partial y} = g(y, t)$$

— (17)

This implies the total derivative of $F(y, t)$

$$dF(y, t) = \frac{\partial F}{\partial y} dy + \frac{\partial F}{\partial t} dt$$

$$\frac{dF}{dt} = \frac{\partial F}{\partial y} \cdot \frac{dy}{dt} + \frac{\partial F}{\partial t} \cdot \frac{dt}{dt}$$

$$\frac{dF}{dt} = \frac{\partial F}{\partial y} \frac{dy}{dt} + \frac{\partial F}{\partial t} \quad (17)$$

$$\frac{dF}{dt} = \underbrace{g(y, t) \frac{dy}{dt} + f(y, t)}_{\text{LHS of (16)}}$$

$$\frac{dF(y, t)}{dt} = 0 \Leftrightarrow F(y, t) = \text{constant } C$$

The general solⁿ should be $F(y, t) = C$

Ex $2ty dy + y^2 dt = 0 \checkmark \checkmark \checkmark$

or $2ty \frac{dy}{dt} + y^2 = 0$

$g(y, t) \cdot \frac{dy}{dt} + f(y, t) = 0$

$g(y, t) = 2ty = \frac{\partial F}{\partial y} \rightarrow \frac{\partial F}{\partial y \partial t} = 2y = \frac{\partial g}{\partial t} \text{ (a)}$

$$f(y, t) = y^2 = \frac{\partial F}{\partial t} \rightarrow \frac{\partial^2 F}{\partial t \partial y} = 2y = \frac{\partial F}{\partial y} - (b)$$

we are going to solve for $y(t)$

ψ - psi
 ϕ - phi
 ω

Let $g(y, t) = \frac{\partial F}{\partial y} = M$

$$F(y, t) = \int M dy + \psi(t)$$

$$C = \int M dy + \psi(t)$$

step i

$$F(y, t) = \int M dy + \psi(t)$$

$$= \int 2ty dy + \psi(t)$$

$$F(y, t) = y^2 t + C_1 + \psi(t) - (A)$$

step ii

derivative (*)

w.r.t. t

From (b)

$$\frac{\partial F(y, t)}{\partial t} = y^2 + \psi'(t) - (AA)$$

$$f(y, t) = y^2 = \frac{\partial F}{\partial t} - (b)$$

$$y^2 = y^2 + \psi'(t)$$

$$\psi'(t) = 0$$

step iii $\psi(t) = \int \psi'(t) dt$
 $= \int 0 dt$
 $\psi(t) = C_2$

step iv go back to step i and sub $\psi(t) = C_2$ into (*)

$$F(y, t) = y^2 t + C_2 + C_1$$

$$F(y, t) = y^2 t + C_3 \quad ; \quad C_3 = C_2 + C_1$$

we know $F(y, t) = C$

$$C = y^2 t + C_3$$

$$y^2 t = C_4 \quad ; \quad C_4 = C - C_3$$

$$y^2 = C_4 t^{-1}$$

\therefore $y(t) = C_5 t^{-\frac{1}{2}} \quad ; \quad C_5 = (C_4)^{\frac{1}{2}}$

check
 $2ty \left(\frac{dy}{dt} \right) + y^2 = 0$

$$y'(t) = -\frac{1}{2} C_5 t^{-\frac{3}{2}}$$

$$2t \left(C_5 t^{-\frac{1}{2}} \right) \left(-\frac{1}{2} C_5 t^{-\frac{3}{2}} \right) + \left(-\frac{1}{2} C_5 t^{-\frac{3}{2}} \right)^2 = 0$$

$$\frac{dy}{dt} + u(t)y(t) = w(t)$$

$$\frac{dy}{dt} + (uy - w) = 0 \quad \text{--- } (\star)$$

From

$$g(y,t) \frac{dy}{dt} + f(y,t) = 0$$

$$g(y,t) = 1 = \frac{\partial F}{\partial y} \rightarrow \frac{\partial^2 F}{\partial y \partial t} = 0 \quad \left. \begin{array}{l} \text{not exact} \\ \vdots \end{array} \right\}$$

$$f(y,t) = u(t)y(t) - w(t) = \frac{\partial F}{\partial t} \rightarrow \frac{\partial^2 F}{\partial t \partial y} = u(t)$$

We can make (\star) exact DE by premultiplying by $I(t)$ "integrating factor"

(\star) becomes

$$\underbrace{I(t)}_{g(y,t)} \frac{dy}{dt} + \underbrace{I(t)[u(t)y(t) - w(t)]}_{f(y,t)} = 0$$

$$\frac{\partial^2 F}{\partial y \partial t} = \frac{\partial g}{\partial t} = \frac{dI(t)}{dt} \quad \left. \right\}$$

$$\frac{\partial^2 F}{\partial t \partial y} = \frac{\partial F}{\partial y} = I(t) u(t) \quad \left. \vphantom{\frac{\partial^2 F}{\partial t \partial y}} \right\} \frac{dI}{dt} = I(t) u(t)$$

$$\frac{1}{I} \frac{dI}{dt} = u(t)$$

$$\int \frac{1}{I} \frac{dI}{dt} dt = \int u(t) dt$$

$$\ln |I| = -c + \int u(t) dt$$

$$e^{\ln |I|} = e^{-c} e^{\int u(t) dt}$$

$$\boxed{I(t) = A e^{\int u(t) dt}} \quad A = e^{-c}$$

Assuming that $A = 1$

(A) becomes

$$e^{\int u(t) dt} \frac{dy}{dt} + e^{\int u(t) dt} [u(t)y(t) - w(t)] = 0$$

$$g(y, t) = \frac{\partial F}{\partial y} = M = e^{\int u(t) dt}$$

$$f(y, t) = \frac{\partial F}{\partial t} = e^{\int u(t) dt} [u(t)y(t) - w(t)]$$

step i $F(y,t) = \int M dy + \psi(t) \quad (A1)$

$$= \int e^{\int u(t) dt} dy + \psi(t)$$

$$= \left[e^{\int u(t) dt} \cdot y + C \right] + \psi(t)$$