

# EE320 (2/2012)

## INTRODUCTORY MATHEMATICAL ECONOMICS

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OPTIMIZATION WITHOUT CONSTRAINTS:

MORE-THAN-ONE-INDEPENDENT VARIABLE CASES

(Additional materials)

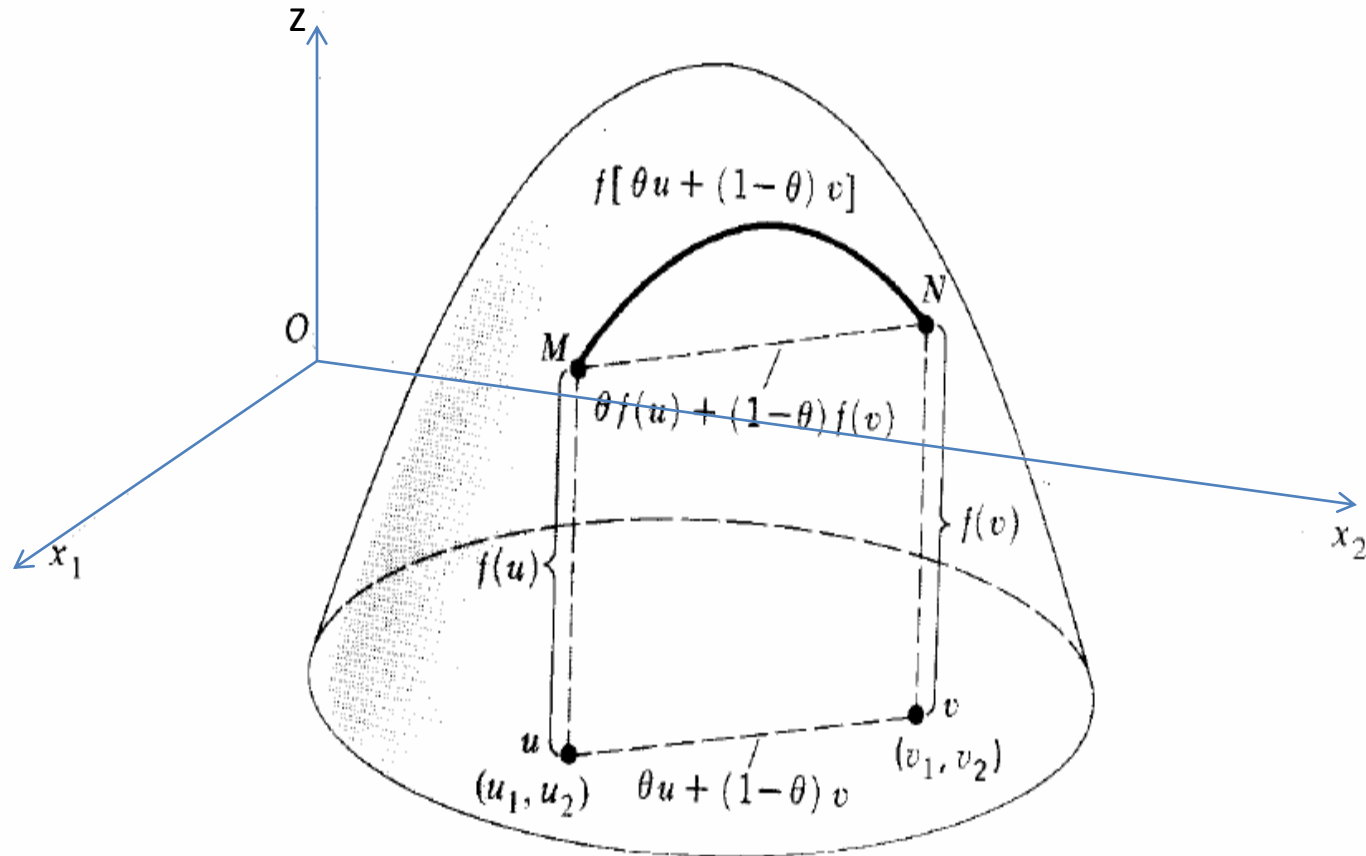
# Topics

- Second-order conditions in relations to concavity and convexity
- Comparative-static aspects of optimization

# Checking Concavity and Convexity

- Consider a two-variable function  $z = f(x_1, x_2)$ .
- **Definition:**
  - The function is *concave* (*convex*) if and only if, for any pair of distinct points M and N on its graph – surface – line segment MN lies either *on or below* (*above*) the surface.
  - The function is *strictly concave* (*strictly convex*) if and only if line segment MN lies *entirely below* (*above*) the surface, except at M and N.

# Strictly Concave Function



A function  $f$  is **strictly concave** (**convex**) iff, for any pair of distinct points  $u$  and  $v$  in the domain of  $f$ , and for  $0 < \theta < 1$ ,

$$\theta f(u) + (1 - \theta)f(v) < (>) f[\theta(u) + (1 - \theta)(v)]$$

# Theorems on Concavity and Convexity

- **Theorem 1** (Linear Function)

If  $f(x)$  is a linear function, then it is a concave function as well as a convex function, but not strictly so.

- **Theorem 2** (Negative of a Function)

If  $f(x)$  is a concave function, then  $-f(x)$  is a convex function, and vice versa. Similarly, if  $f(x)$  is a strictly concave function, then  $-f(x)$  is a strictly convex function

- **Theorem 3** (Sum of Functions)

If  $f(x)$  and  $g(x)$  are both concave (convex) functions, then  $f(x) + g(x)$  is also a concave (convex) function. If  $f(x)$  and  $g(x)$  are both strictly concave (strictly convex) functions, then  $f(x) + g(x)$  is a strictly concave (strictly convex) function.

# Differentiable Functions

- Consider a one-variable function  $z = f(x)$ ,

A differentiable function  $f(x)$  is *concave* (*convex*) iff, for any given point  $u$  and any other point  $v$  in the domain,

$$f(v) \leq (\geq) f(u) + f'(u)(v-u)$$

[Figure 11.7]

- Consider a function  $f(x) = f(x_1, \dots, x_n)$ ,

A differentiable function  $f(x_1, \dots, x_n)$  is *concave* (*convex*) iff, for any given point  $u = (u_1, \dots, u_n)$  and any other point  $v = (v_1, \dots, v_n)$  in the domain,

$$f(v) \leq (\geq) f(u) + \sum_j f_j(u)(v_j - u_j), \text{ where } f_j(u) = \partial f / \partial x_j$$

# Checking Concavity and Convexity by the Derivative Conditions

- Consider a function  $z = f(x_1, \dots, x_n)$ , which is twice continuously differentiable. For such a function, second-order partial derivatives exist, and thus  $d^2z$  is defined.
- Concavity and convexity can then be checked by the sign of  $d^2z$ :

A twice continuously differentiable function  $z = f(x_1, \dots, x_n)$  is *concave (convex)* if, and only if,  $d^2z$  is everywhere *negative (positive) semidefinite*.

The said function is *strictly concave (strictly convex)* if (but not only if)  $d^2z$  is everywhere *negative (positive) definite*.

# Examples

Check the following functions for concavity and convexity by the derivative conditions.

- **Example 1**:  $z = -x^4$
  
  
  
  
  
  
  
  
  
  
- **Example 2**:  $z = x_1^2 + x_2^2$

# Comparative-Static Aspects of Optimization

Example: Consider a two-product firm in perfect competition.  
 The firm's revenue is  $R = P_{10}Q_1 + P_{20}Q_2$  ( $P_{10}$  and  $P_{20}$  are exogenous)  
 And the cost function is  $C = 2Q_1^2 + Q_1Q_2 + 2Q_2^2$ .

→ **Reduced-form solutions** are the optimal output levels expressed in terms of exogenous variables ( $P_{10}$  and  $P_{20}$ ):

$$Q_1^* = \quad \text{and} \quad Q_2^* =$$

→ Comparative-statics of the model:

$$\frac{\partial Q_1^*}{\partial P_{10}} = \quad ; \frac{\partial Q_1^*}{\partial P_{20}} = \quad ; \frac{\partial Q_2^*}{\partial P_{10}} = \quad ; \frac{\partial Q_2^*}{\partial P_{20}} =$$

# Comparative-Static Aspects of Optimization

- General-Function Models

Consider the input-decision problem. Given that  $R = P \cdot Q(K, L)$  and  $C = wL + rK$ , where  $P$ ,  $w$ , and  $r$  are exogenous, find  $\partial L^*/\partial P$  and  $\partial K^*/\partial P$ .