

System Equations Estimation Methods

After finish this session, you should

understand:

- - Finite Sample Unbiased vs Asymptotic Consistent vs Relative Efficient ✓
- - The differences between Single vs System equations estimation methods
 - Instrumental Variables (IV) technique
 - OLS vs ILS vs 2SLS vs 3SLS
 - ✓ - Seemingly Unrelated Models
 - - Simultaneous Equations Models

System Equations Estimation Methods

System Equations Models

- ✓ Seemingly Unrelated (SUR) Model
- ✓ Simultaneous Equations Model
 - Limited Information Estimation Methods
(Single Equation Estimation Methods)
 - ILS, 2SLS, & LIML
 - Full Information Estimation Methods
(System Equation Estimation Methods)
 - 3SLS, LSLS, & (FIML)

System Equations Estimation Methods

100 1,000 10,000

1,000,000

Finite Sample (Small Sample) Properties

Unbiased $E(\hat{\beta}) = \beta$ (All sizes of sample)

Asymptotic (Large Sample) Properties

Consistent $p \lim(\hat{\beta}) = \beta$

$\lim_{n \rightarrow \infty} \Pr(\hat{\beta} - \beta = \varepsilon) = 0$ where $\varepsilon \neq 0, \varepsilon \rightarrow 0$

(Only when $n \rightarrow \infty$)

$\hat{\beta} = \beta$
 $p \lim_{n \rightarrow \infty} \hat{\beta} = \beta$

Relative Properties

Efficient $\text{var}(\hat{\beta}) < \text{var}(\hat{\beta}_{\text{other}})$

(Compare with ...)

OLS
↓
BLUE
consistent
 $n \rightarrow \infty$

Seemingly Unrelated Regression (SUR) Models

The models:

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} = \begin{bmatrix} X_1 & 0 & \cdots & 0 \\ 0 & X_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & X_m \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_m \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_m \end{bmatrix}$$

or

$$y = X\beta + \varepsilon$$

where

$$E[\varepsilon] = 0, \text{var}(\varepsilon) = \Sigma = \begin{bmatrix} \sigma_{11}I & \sigma_{12}I & \cdots & \sigma_{1m}I \\ \sigma_{21}I & \sigma_{22}I & \cdots & \sigma_{2m}I \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{m1}I & \sigma_{m2}I & \cdots & \sigma_{mm}I \end{bmatrix}$$

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Seemingly Unrelated Regression (SUR) Models

The models:

$$\begin{bmatrix} y_{11} \\ y_{12} \\ \vdots \\ y_{1t_1} \\ y_{21} \\ y_{22} \\ \vdots \\ y_{2t_2} \\ \vdots \\ y_{m1} \\ y_{m2} \\ \vdots \\ y_{mt_m} \end{bmatrix} = \begin{bmatrix} 1 & X_{111} & \cdots & X_{1k_11} \\ 1 & X_{112} & \cdots & X_{1k_12} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & X_{11t_1} & \cdots & X_{1k_1t_1} \\ 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \\ 1 & X_{211} & \cdots & X_{2k_21} \\ 1 & X_{212} & \cdots & X_{2k_22} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & X_{21t_2} & \cdots & X_{2k_2t_2} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \\ 1 & X_{m11} & \cdots & X_{mk_m1} \\ 1 & X_{m12} & \cdots & X_{mk_m2} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & X_{m1t_m} & \cdots & X_{mk_mt_m} \end{bmatrix} \begin{bmatrix} \beta_{10} \\ \beta_{11} \\ \vdots \\ \beta_{1k_1} \\ \beta_{20} \\ \beta_{21} \\ \vdots \\ \beta_{2k_2} \\ \vdots \\ \beta_{m0} \\ \beta_{m1} \\ \vdots \\ \beta_{mk_m} \end{bmatrix} + \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{12} \\ \vdots \\ \varepsilon_{1t_1} \\ \varepsilon_{21} \\ \varepsilon_{22} \\ \vdots \\ \varepsilon_{2t_2} \\ \vdots \\ \varepsilon_{m1} \\ \varepsilon_{m2} \\ \vdots \\ \varepsilon_{mt_m} \end{bmatrix}$$

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Seemingly Unrelated Regression (SUR) Models

$$\text{var}(\varepsilon) = \Sigma = \begin{bmatrix} \begin{bmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_1^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_1^2 \end{bmatrix} & \begin{bmatrix} \sigma_{12} & 0 & \dots & 0 \\ 0 & \sigma_{12} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{12} \end{bmatrix} & \dots & \begin{bmatrix} \sigma_{1m} & 0 & \dots & 0 \\ 0 & \sigma_{1m} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{1m} \end{bmatrix} \\ \begin{bmatrix} \sigma_{21} & 0 & \dots & 0 \\ 0 & \sigma_{21} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{21} \end{bmatrix} & \begin{bmatrix} \sigma_2^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_2^2 \end{bmatrix} & \dots & \begin{bmatrix} \sigma_{2m} & 0 & \dots & 0 \\ 0 & \sigma_{2m} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{2m} \end{bmatrix} \\ \vdots & \vdots & \ddots & \vdots \\ \begin{bmatrix} \sigma_{m1} & 0 & \dots & 0 \\ 0 & \sigma_{m1} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{m1} \end{bmatrix} & \begin{bmatrix} \sigma_{m2} & 0 & \dots & 0 \\ 0 & \sigma_{m2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{m2} \end{bmatrix} & \dots & \begin{bmatrix} \sigma_m^2 & 0 & \dots & 0 \\ 0 & \sigma_m^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_m^2 \end{bmatrix} \end{bmatrix}$$

Seemingly Unrelated Regression (SUR) Models

✓ reg y_1 x_1 x_2

Example: System of two equations: ✓ reg y_2 x_2 x_3

$$\begin{aligned} \textcircled{1} \quad y_{1t} &= \beta_{10} + \beta_{11}x_{1t} + \beta_{12}x_{2t} + \varepsilon_{1t} \\ y_{2t} &= \beta_{20} + \beta_{22}x_{2t} + \beta_{23}x_{3t} + \varepsilon_{2t} \end{aligned}$$

Diagram illustrating the relationship between error terms ε_{1t} and ε_{2t} . A blue oval encloses ε_{1t} and ε_{2t} , with an arrow pointing to a summation symbol $\Rightarrow \Sigma$, indicating a relationship or correlation between the error terms.

If there exists relationship of the error terms across equations, i.e. $E(\varepsilon_{1t}\varepsilon_{2t}) \neq 0$.

Ignorance of this problem by using single equation estimation method (or separate OLS) will lead to less efficient estimators.

$$\sqrt{\text{var}(\hat{\beta})} \uparrow = \frac{\sigma}{\text{S.E.} \hat{\beta}} = t\text{-test} \downarrow$$

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Seemingly Unrelated Regression (SUR) Models

Example: System of two equations:

$$\begin{array}{c}
 \begin{matrix} 1 \\ 2 \\ \vdots \\ 104 \end{matrix} \begin{bmatrix} y_{11} \\ y_{12} \\ \vdots \\ y_{1t} \end{bmatrix} \\
 \hline
 \begin{matrix} 101 \\ 102 \\ \vdots \\ 210 \end{matrix} \begin{bmatrix} y_{21} \\ y_{22} \\ \vdots \\ y_{2t} \end{bmatrix}
 \end{array}
 =
 \begin{bmatrix}
 1 & x_{11} & x_{21} \\
 1 & x_{12} & x_{22} \\
 \vdots & \vdots & \vdots \\
 1 & x_{1t} & x_{2t}
 \end{bmatrix}
 \begin{bmatrix}
 0 & 0 & 0 \\
 0 & 0 & 0 \\
 \vdots & \vdots & \vdots \\
 0 & 0 & 0
 \end{bmatrix}
 +
 \begin{bmatrix}
 \beta_{11} \\
 \beta_{12} \\
 \vdots \\
 \beta_{1t}
 \end{bmatrix}
 +
 \begin{bmatrix}
 \varepsilon_{11} \\
 \varepsilon_{12} \\
 \vdots \\
 \varepsilon_{1t}
 \end{bmatrix}$$

The diagram illustrates a system of two equations. The first equation (top) has a dependent variable vector y_1 (rows 1 to 104) and an independent variable matrix X_1 (rows 1 to 104, columns 1 to 3). The second equation (bottom) has a dependent variable vector y_2 (rows 101 to 210) and an independent variable matrix X_2 (rows 101 to 210, columns 1 to 3). The error term vector ε is shown on the right. The parameters β_1 and β_2 are shown in the middle. The matrix X is circled in blue. The error term ε is circled in blue.

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If there exists relationship of the error terms across equations, i.e. $E(\varepsilon_{1t}\varepsilon_{2t}) = \sigma_{12} \neq \sigma_{21} \neq 0$

$$\text{var}(\varepsilon) = \Sigma = \begin{bmatrix} \Sigma_1 & \Sigma_{12} \\ \Sigma_{21} & \Sigma_2 \end{bmatrix} = \begin{bmatrix} \begin{bmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_1^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_1^2 \end{bmatrix} & \begin{bmatrix} \sigma_{12} & 0 & \dots & 0 \\ 0 & \sigma_{12} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{12} \end{bmatrix} \\ \begin{bmatrix} \sigma_{21} & 0 & \dots & 0 \\ 0 & \sigma_{21} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{21} \end{bmatrix} & \begin{bmatrix} \sigma_2^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_2^2 \end{bmatrix} \end{bmatrix}$$

The diagram illustrates the variance-covariance matrix Σ for a Seemingly Unrelated Regression (SUR) model. The matrix is partitioned into four blocks: Σ_1 , Σ_{12} , Σ_{21} , and Σ_2 . The diagonal blocks Σ_1 and Σ_2 are diagonal matrices representing the variances of the error terms for each equation. The off-diagonal blocks Σ_{12} and Σ_{21} represent the covariances between the error terms of the two equations. The diagram highlights the relationship $\sigma_{12} \neq \sigma_{21} \neq 0$ with red and blue annotations, indicating that the error terms are correlated across equations.

Estimation of SUR Models

Two-step system estimation or FGLS

1. Estimate Var-Cov matrix $\hat{\Sigma}$
2. Estimate all parameters β_j using FGLS.

$$\hat{\beta}_{SUR} = \hat{\beta}_{FGLS} = \left(\underline{X} (\hat{\Sigma}^{-1}) \underline{X}' \right)^{-1} \underline{X}' \hat{\Sigma}^{-1} y$$

Then, system equation estimation method will provide a more asymptotically efficient estimators.

$\text{Var}(\hat{\beta}_{FGLS}) < \text{Var}(\hat{\beta}_{OLS})$
 $\text{as } n \rightarrow \infty$

☆☆☆ However, if there exists specification error problem in any equations, the problem will spread through out the whole system.

Simultaneous Equations Model

More than one equation.

Jointly dependent or endogenous variables.

General Structural Form model can be stated as:

Exogenous.

$$\gamma_{11}\underline{y_{t1}} + \gamma_{21}\underline{y_{t2}} + \cdots + \gamma_{m1}\underline{y_{tm}} + \beta_{11}\underline{x_{t1}} + \cdots + \beta_{k1}\underline{x_{tk}} = \varepsilon_{t1}$$

$$\gamma_{12}y_{t1} + \gamma_{22}y_{t2} + \cdots + \gamma_{m2}y_{tm} + \beta_{12}x_{t1} + \cdots + \beta_{k2}x_{tk} = \varepsilon_{t2}$$

⋮

$$\gamma_{1m}y_{t1} + \gamma_{2m}y_{t2} + \cdots + \gamma_{mm}y_{tm} + \beta_{1m}x_{t1} + \cdots + \beta_{km}x_{tk} = \varepsilon_{tm}$$

Simultaneous Equations Model

Structural Form model:

$$\begin{aligned}
 & \underline{[y_1 \quad y_2 \quad \cdots \quad y_m]_t} \begin{bmatrix} \gamma_{11} & \gamma_{12} & \cdots & \gamma_{1m} \\ \gamma_{21} & \gamma_{22} & \cdots & \gamma_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ \gamma_{m1} & \gamma_{m2} & \cdots & \gamma_{mm} \end{bmatrix} + \\
 & \underline{[x_1 \quad x_2 \quad \cdots \quad x_m]_t} \begin{bmatrix} \beta_{11} & \beta_{12} & \cdots & \beta_{1m} \\ \beta_{21} & \beta_{22} & \cdots & \beta_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ \beta_{m1} & \beta_{m2} & \cdots & \beta_{mm} \end{bmatrix} = [\varepsilon_{1t} \quad \varepsilon_{2t} \quad \cdots \quad \varepsilon_{mt}]
 \end{aligned}$$

or

$$\underline{y_t'} \Gamma + \underline{x_t'} B = \underline{\varepsilon_t'}$$

Simultaneous Equations Model

Two endogenous variables models:

$$\begin{aligned}
 y_{1t} &= \beta_{10} + \beta_{12} y_{2t} + \gamma_{11} x_{1t} + \varepsilon_{1t} \\
 y_{2t} &= \beta_{20} + \beta_{21} y_{1t} + \gamma_{21} x_{1t} + \varepsilon_{2t}
 \end{aligned}$$

Endogeneity
Bias.

$$E(\varepsilon_{1t} y_{2t}) \neq 0$$

$$E(\varepsilon_{2t} y_{1t}) \neq 0$$

Example

Keynesian Income Determination Model

Consumption Function

Income Identity

$$\underline{C_t} = \beta_0 + \beta_1 \underline{Y_t} + \varepsilon_{1t}$$

$$\underline{Y_t} = \underline{C_t} + \underline{I_t}$$

$$E(\varepsilon_{1t} \varepsilon_{2t}) \neq 0$$

System Equations Model

Simultaneous Bias occurs when $E(y_t \varepsilon_{1t}) \neq 0$

OLS estimators will be biased, inconsistent, and inefficient.

$$E(\hat{\beta}) \neq \beta \quad \text{Biased}$$

$$p \lim(\hat{\beta}) \neq \beta \quad \text{Inconsistent}$$

System Equations Model

Structural Form Model
shows structural
relationship between
endogenous variables
and exogenous variables
& lagged endogenous
variables.

Theory

(2) $C_t = \beta_0 + \beta_1 Y_t + \varepsilon_{1t}$

Identity

$$Y_t \equiv C_t + I_t$$

$$C_t = \beta_0 + \beta_1 (C_t + I_t) + \varepsilon_{1t}$$

$$C_t - \beta_1 C_t = \beta_0 + \beta_1 I_t + \varepsilon_{1t}$$

$$(1 - \beta_1) C_t = \beta_0 + \beta_1 I_t + \varepsilon_{1t}$$

$$C_t = \frac{\beta_0}{(1 - \beta_1)} + \frac{\beta_1}{(1 - \beta_1)} I_t + \frac{\varepsilon_{1t}}{(1 - \beta_1)}$$

$$C_t = \pi_0 + \pi_1 I_t + w_{1t}$$

Reduced Form Model
shows relationship only
between endogenous
variables and exogenous
variables.

(1) $C_t = \pi_0 + \pi_1 I_t + w_{1t}$
 $Y_t = \pi_2 + \pi_3 I_t + w_{2t}$

where

$$\pi_0 = \frac{\beta_0}{1 - \beta_1}$$

$$\pi_1 = \frac{\beta_1}{1 - \beta_1}$$

$$\pi_3 = \frac{1}{1 - \beta_1}$$

$$\pi_2 = \frac{\beta_0}{1 - \beta_1}$$

$$w_{1t} = \frac{\varepsilon_{1t}}{1 - \beta_1}$$

$$w_{2t} = \frac{\varepsilon_{1t}}{1 - \beta_1}$$

System Equations Model

Identification problem:

✓ - Over-identified system

✓ - Exactly-identified system

✓ - Under-identified system

3 eq. & 2 unk. →

more
than
1 sol.

2 eq. & 2 unk. →

unique
solution.

2 eq. & 3 unk.

→ can't
solve

Sol. no. sol.

Single Equation Estimation Methods

→ Indirect Least Squares (ILS) *unique solution*

Only for exactly-identified system

- Estimate Reduced form model using OLS
- Solve for estimated β

Structural Form Model:

$$Y\Gamma + XB = E$$

Reduced Form Model:

$$Y = X\hat{\Pi} + V$$

ILS: 1. Estimate Reduced Form $\hat{\Pi} = (X'X)^{-1} X'Y$

2. Solve for B

$$\underline{\hat{B}_{ILS}} = -\underline{\hat{\Pi}\Gamma}$$

Single Equation Estimation Methods

Two-Stage Least Squares (2SLS) *more than 1 sol.*

For both Exactly and Over-identified systems

1. Estimate Reduced form model using OLS

Predict endogenous variable ($\hat{Y}$)

2. Use $\hat{Y}$ as Instrumental Variables (IV) for lagged endogenous variables instead of using actual Y , then, obtain matrix $\hat{Z}$, then estimate model using IV technique

$$\hat{B} = (\hat{Z}'\hat{Z})^{-1} \hat{Z}'Y$$

System Equations Estimation Methods

Three-Stage Least Squares (3SLS)

If there exists relationship of the error terms across equations, system equation estimation will lead to more asymptotically efficient estimators.

2SLS + construct estimated Σ matrix

3-stage perform FGLS using estimated $\hat{\Sigma}$ matrix

$$\hat{B} = \left[\hat{Z}' (\hat{\Sigma}^{-1}) \hat{Z} \right]^{-1} \hat{Z}' (\hat{\Sigma}^{-1}) y$$

OLS, ILS, 2SLS, 3SLS

① OLS ✓
② IV ✓

Run One eq. at a time ③ FGLS

Whole system

① Single Equation Estimation Methods

OLS: biased, inconsistent, & inefficient

ILS: biased, consistent, & Asymptotically efficient

2SLS: biased, consistent, & Asymptotically efficient

② System Equation Estimation Methods

Run all eq (models) in 1 time.

~~3SLS~~: biased, consistent?, & More Asymptotically

efficient if there exists correlation of error terms across eq.

☆☆☆ but if there exists specification error in one or any equation(s), the specification error problem will spread through all equations in the system

→ Inconsistent.

Specification Test – Hausman Test

Hypothesis OLS estimators are consistent compared to alternative method estimators.

Reject H_0 means there is exists endogeneity (simultaneous) bias (or x 's are endogenous).

Fail to Reject H_0 means there is no endogeneity (simultaneous) bias (or x 's are exogenous).