

Last time

2.1.4	Exact DE	} possible non-linear DE
2.1.5	Separable DE	
2.1.6	Bernoulli's Equation	

$$y'(t) + u(t) \cdot y(t) = w(t) [y(t)]^r \quad (1) \quad \checkmark$$

$r \neq 1$  and  $r \neq 0$

$$\text{Let } z(t) = [y(t)]^{1-r} \quad \leftrightarrow \quad y(t) = [z(t)]^{\frac{1}{1-r}}$$

(1) becomes

$$\frac{1}{1-r} z'(t) + u(t) z(t) = w(t) \quad (2)$$

$$\text{or } z'(t) + (1-r)u(t) z(t) = (1-r)w(t)$$

Ex

$$y'(t) + t \cdot y(t) = 3t [y(t)]^2$$

$$r = 2$$

$$z(t) = [y(t)]^{1-r} = [y(t)]^{1-2} = y^{-1}$$

$$y(t) = z(t)^{-1}$$

From (2)

$$\frac{1}{1-r} z'(t) + u(t) z(t) = w(t)$$

$$u(t) = t \quad w(t) = 3t$$

$$\frac{1}{1-2} z'(t) + t z(t) = 3t$$

$$(-1) z'(t) + t z(t) = 3t$$

$$z'(t) - t z(t) = -3t$$

Next?

Find  $y(t) = [z(t)]^{-1}$

$$z(t) = e^{-\int f(t) dt} \left[ A + \int e^{\int f(t) dt} w(t) dt \right]$$

OR

$$z'(t) = (z-3)t \quad \text{separable}$$

step i

$$g(z) = z-3$$

$$f(t) = t$$

step ii

$$\frac{1}{z-3} z'(t) = t$$

step iii

$$\int \frac{1}{z-3} dz = \int t dt$$

step iv

$$\ln|z-3| + C_1 = \frac{t^2}{2} + C_2$$

$$\ln|z-3| = \frac{t^2}{2} + C \quad ; \quad C = C_2 - C_1$$

$$e^{\ln|z-3|} = e^{\frac{t^2}{2} + C}$$

$$z(t) = A e^{\frac{t^2}{2}} + 3; \quad A = e^C$$

$$y(t) = [Ae^{t^2} + 3]^{-1}$$

What if you use formula

---

$$\underline{\text{Ex}} \quad y'(t) + \frac{1}{t}y(t) = [y(t)]^3$$

$$r \neq 1; \quad r = 3$$

$$\frac{1}{1-r} z'(t) + u(t)z(t) = w(t)$$

$$z'(t) - 2t^{-1}z(t) = -2$$

$$u(t) = -2t^{-1} \quad w(t) = -2$$

---

$$y(t) = (At^2 + 2t)^{-\frac{1}{2}}$$

---

$$\underline{\text{Ex}} \quad y'(t) = -ty + t^3y^3$$

---

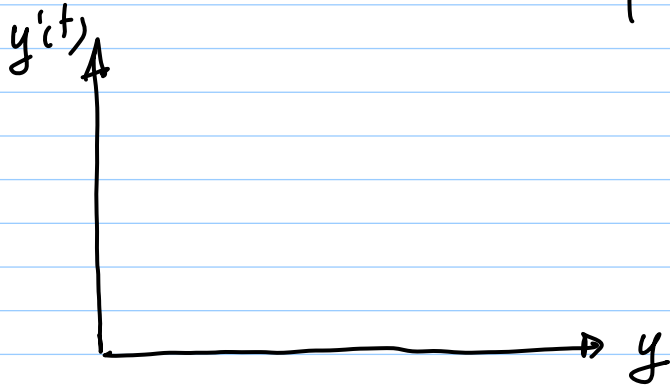
so far, quantitative analysis

## 2.1.7 The Qualitative - Graphical Analysis

General Form  $\frac{dy}{dt} = F(y, t)$

An Autonomous function.  $\frac{dy}{dt} = f(y)$

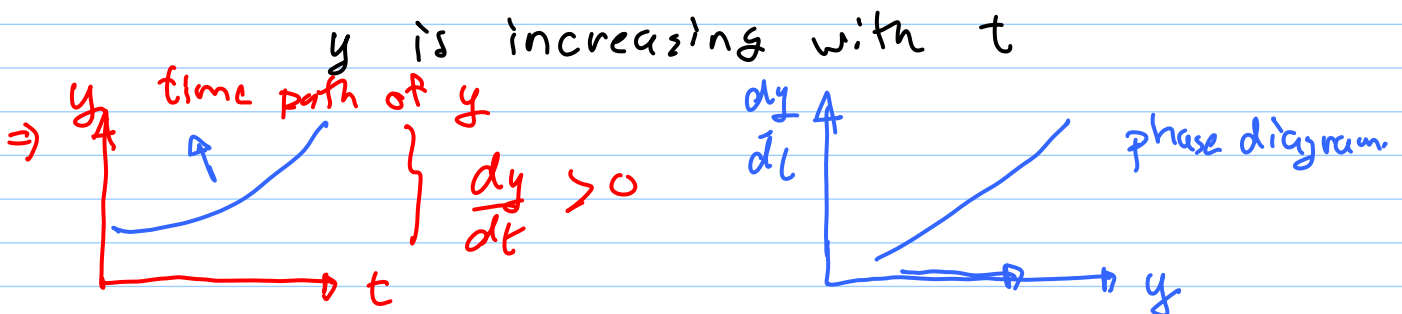
Note  $y = f(x)$  we can plot  $y$  against  $x$   
 $y'(t) = f(y)$  
 $\underbrace{\hspace{10em}}_{y(t)}$   $\underbrace{\hspace{10em}}_y$   
 $\underbrace{\hspace{20em}}$   
 phase diagram



Two general remarks

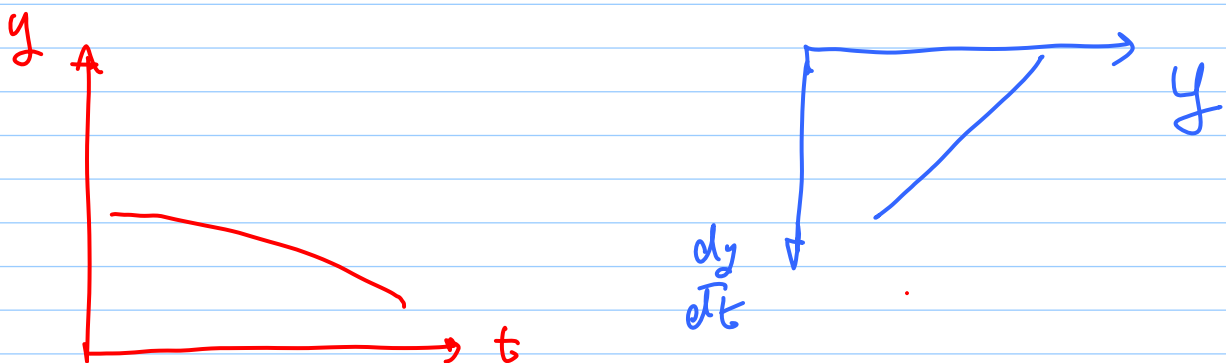
(R1) Anywhere ABOVE the horizontal axis  $\Rightarrow \frac{dy}{dt} > 0$

overtime  $y$  is increasing



Anywhere BELOW the horizontal axis  $\Rightarrow \frac{dy}{dt} < 0$

$y$  is decreasing with  $t$

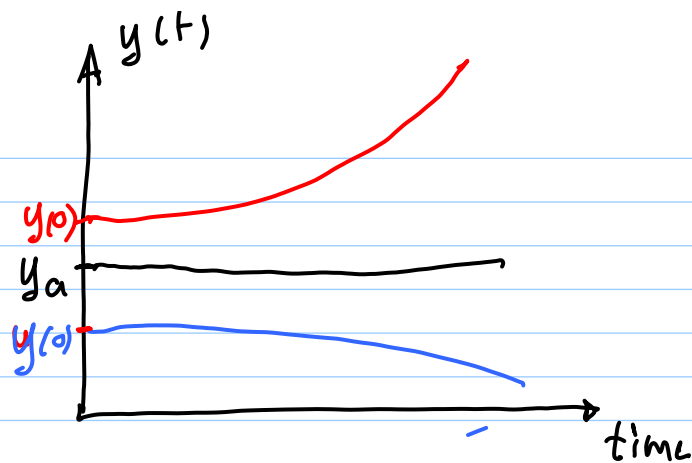
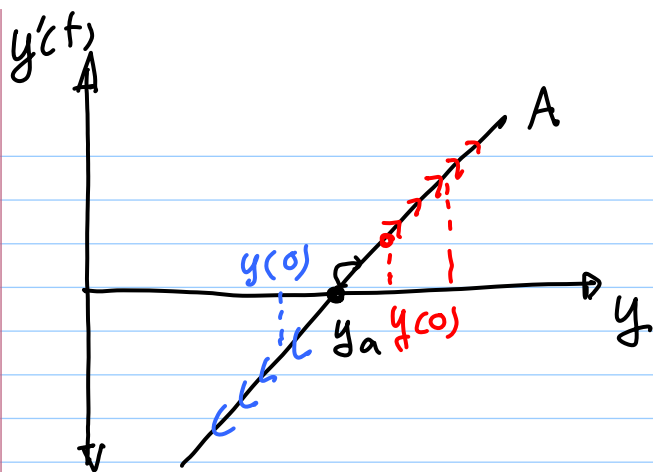


(R2) An equilibrium level of  $y(t) \Rightarrow$  in the intertemporal sense  $\frac{dy}{dt} = 0$

$y(t)$  is stationary over time,  
if the equilibrium exists

## ⊙ Phase Diagram and Time Path

### ⊂ Phase Line A



If  $y(0) = y_a \Rightarrow$  the equilibrium ( $y_a$ ) can be attained

If not,  $y(0) > y_a \Rightarrow y(t)$  is ever increasing

$y(0) < y_a \Rightarrow y(t)$  is ever decreasing

The equilibrium  $y_a$  is Dynamically UNSTABLE

$$\frac{dy}{dt} + a y = b \quad ; \quad a, b \Rightarrow \text{constants}$$

$$\frac{dy}{dt} = (-a)y + b$$

Slope is  $(-a) \Rightarrow$  Phase line A  $(-a) > 0$

Slope  $> 0$

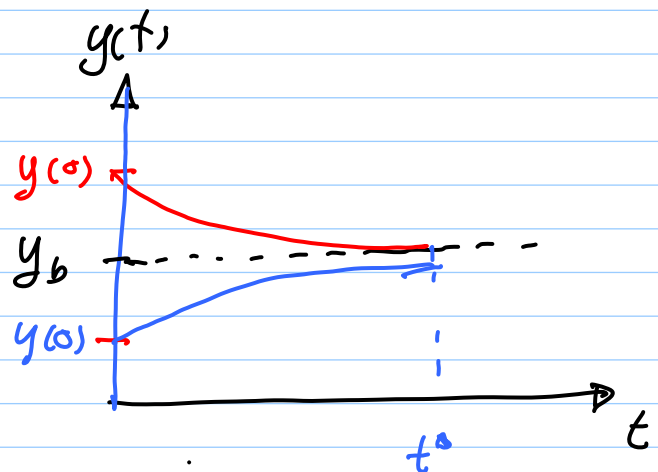
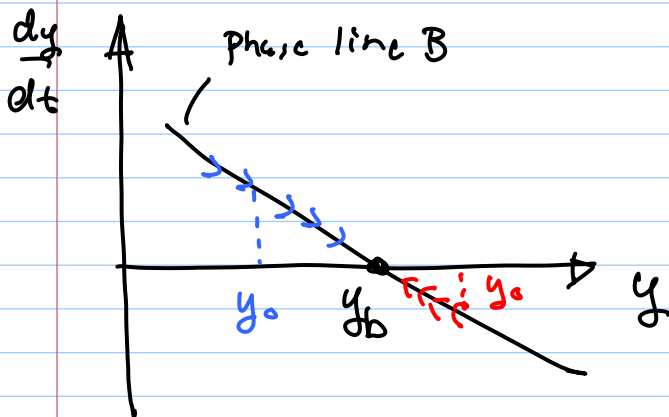
$$a < 0$$

$$y(t) = \left[ y(0) - \frac{b}{a} \right] e^{-at} + \frac{b}{a}$$

$y_c =$  deviation  
from the  
equilibrium

$y_p \Rightarrow$  equilibrium  
level

## (2) Phase Line B



The equilibrium  $y_b$  is Dynamically STABLE.

$$\frac{dy}{dt} = -a y + b$$

slope  $= (-a)$

$\rightarrow$

slope  $< 0$

$-a < 0$

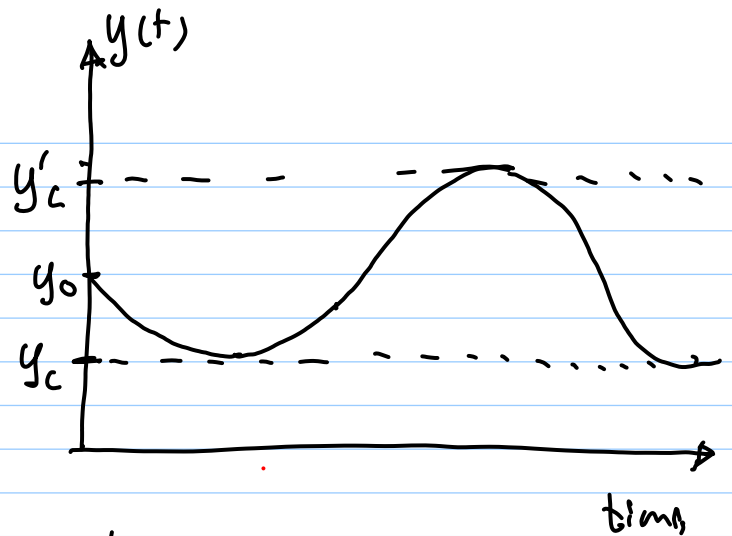
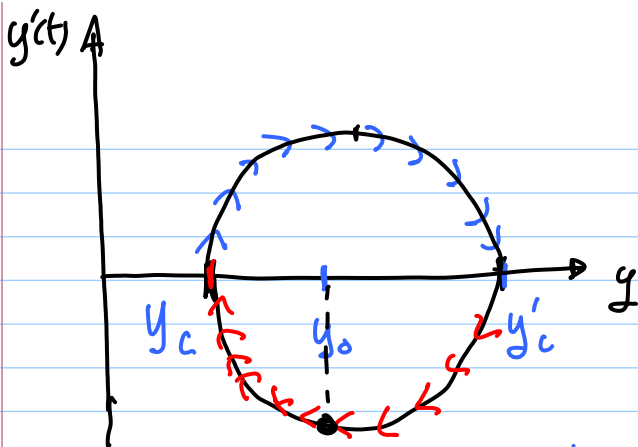
$$a > 0$$

$$y(t) = \left[ y(0) - \frac{b}{a} \right] e^{-at} + \frac{b}{a}$$

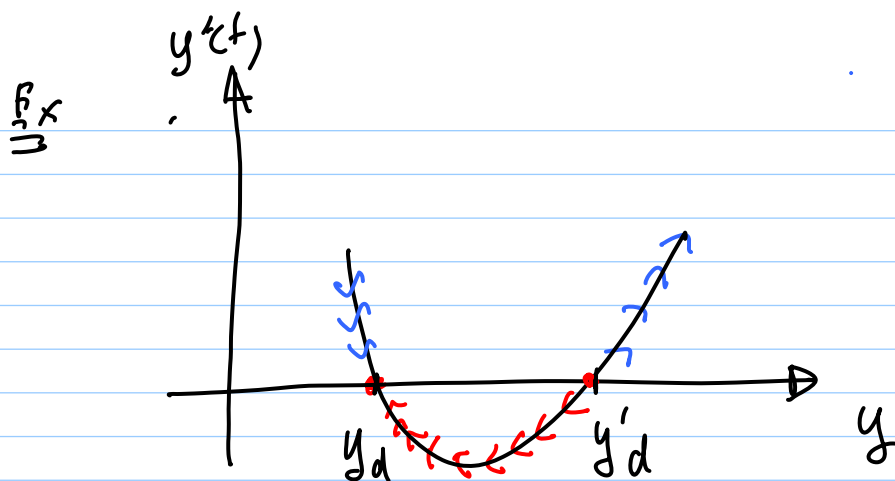
As  $t \rightarrow \infty$ ,  $e^{-at} \rightarrow 0$

$$\Rightarrow y(t) \rightarrow \frac{b}{a} (= y_p)$$

### 3) Phase line C



So  $y_c$  and  $y'_c$  do not represent the equilibrium in the intertemporal sense.



$y_d$  is a locally asymptotically stable equilibrium

$y'_d$  is an unstable equilibrium

### c) The Solow Growth Model

The production function:  $Q = f(K, L) ; K, L > 0$   
— (1)

$Q$  = output       $K$  = capital

$L$  = labor

Note: 3 variables are real variables

$$\Rightarrow f_K > 0 \quad f_L > 0$$

$$[MP_K > 0] \quad [MP_L > 0]$$

$$\Rightarrow f_{KK} < 0 \quad f_{LL} < 0$$

$\Rightarrow$  Assuming linearly homogeneous CRTS  $f^Q$

$$Q = L \cdot f\left(\frac{K}{L}, 1\right)$$

$$= L \phi(k)$$

$$k = \frac{K}{L} = \text{capital-labor ratio}$$

$$= \text{capital per capita.}$$