

CHAPTER 8

Optimization without Constraint: More-Than-One Independent Variable Cases

 Conditions for maximum or minimum

 Third degree price discrimination → multi market

 Competitive Firm Input Choices: Cobb-Douglas Technology → multi factor of production

 Multiproduct-firm ↗ competitive mkt ↘ monopoly

 Multiplant-firm

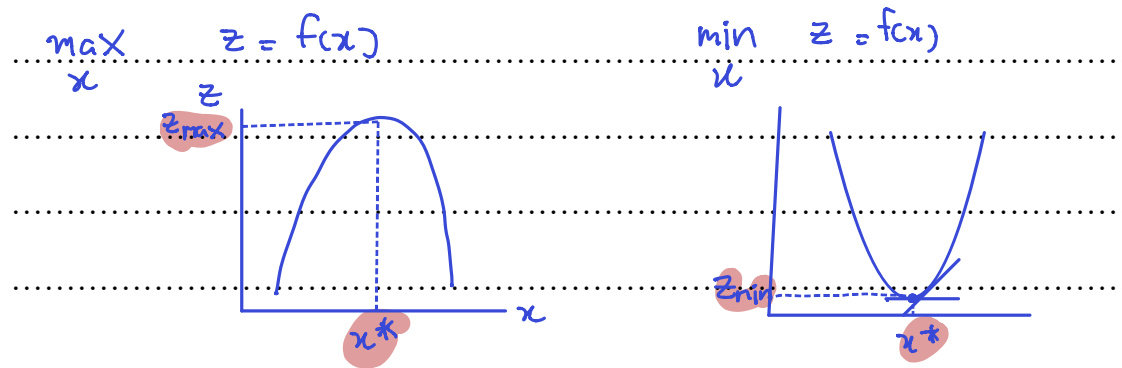


Optimization Condition



One choice variable

The objective function: $z = f(x)$



Condition	Maximum	Minimum
First-order necessary (FONC, FOC)	Derivative $\frac{dz}{dx} = f'(x) = 0$ slope must be zero	Derivative $f'(x) = 0$
	Total differential $dz = \underbrace{f'(x)}_{=0} dx = 0$	Total differential $dz = f'(x) dx = 0$
Second-order sufficient (SOSC, SOC)	Derivative $f''(x) < 0$ slope is decreasing ($0 \rightarrow -$)	Derivative $f''(x) > 0$ slope is increasing ($0 \rightarrow +$)
	Total differential $d^2z < 0$	Total differential $d^2z > 0$

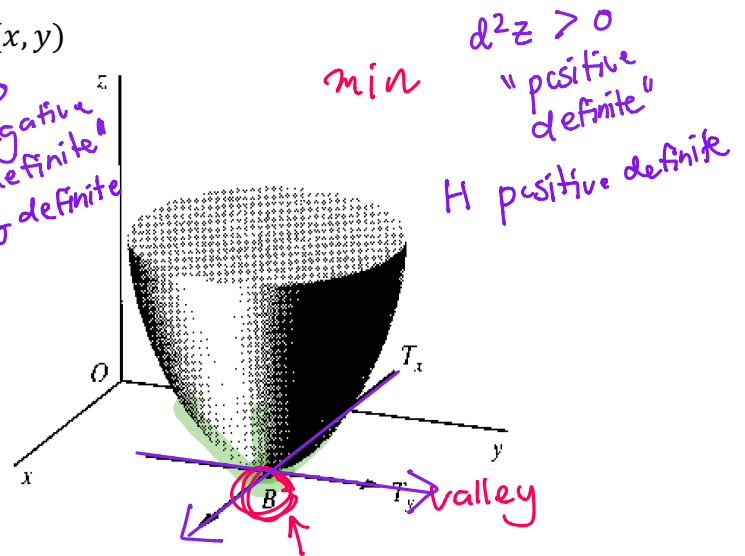
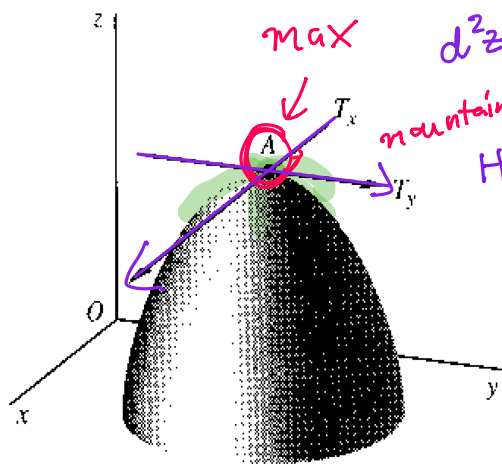
2nd order total differential of z

$$d^2z = f''(x) \underbrace{dx^2}_{>0}$$



Extreme Value of a Function of Two Variables

$$z = f(x, y)$$



First-Order Necessary Condition $z = f(x, y)$

$dz = 0$ for every dx and dy

$$dz = 0$$

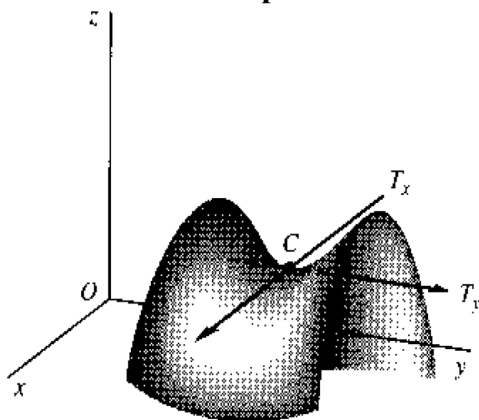
$$\star dz = f_x dx + f_y dy = 0; \quad dx, dy \neq 0$$

$$f_x = 0, \quad f_y = 0$$

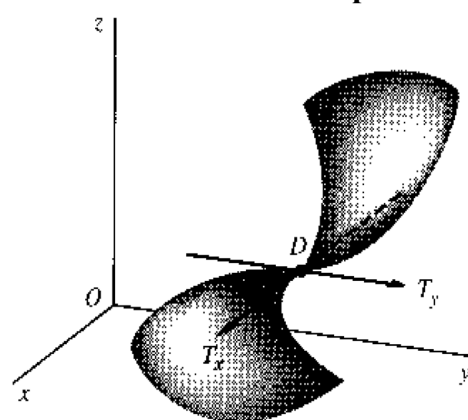
the slope of the tangent line T_x, T_y are zero

The first order necessary condition is necessary, but not sufficient to establish a maximum or a minimum.

Saddle point



Inflection point



Second order sufficient condition

The satisfaction of the first-order condition earmarks certain values of z as the stationary values of the objective function. If at a stationary value of z we find that d^2z is positive definite, i.e., $d^2z > 0$, this will suffice to establish that value of z as a minimum. Analogously, the negative definiteness of d^2z , $d^2z < 0$, is a sufficient condition for the stationary value to be a maximum.

$$y = f(x_1, x_2, \dots, x_n) \quad \begin{matrix} [f_{ij}]_{n \times n} \Rightarrow H_{n \times n} \\ H_{n \times n} \end{matrix}$$

Second-order total differential, Hessian Matrix and Definiteness of Hessian Matrix

📖 About " H_k "

Definition: Let A be an $n \times n$ matrix. A $k \times k$ submatrix, deriving from deleting the last $n - k$ columns and the last $n - k$ rows of matrix A , can be called the k^{th} order leading principal submatrix of matrix A . The corresponding determinant of this $k \times k$ submatrix is called the k^{th} order leading principal minor of matrix A .

The k^{th} order leading principal submatrix of matrix A is denoted by A_k .

The k^{th} order leading principal minor of matrix A is denoted by $|A_k|$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad \begin{matrix} A_1 & A_2 & A_3 \\ 3 \times 3 \end{matrix}$$

Leading principal submatrices are:

The 1^{st} order leading principal submatrix $\Rightarrow$ delete the last $3 - 1$ rows & columns

$$A_1 = [a_{11}]$$

2nd

$$A_2 = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

3rd

$$A_3 = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = A$$

$\Rightarrow$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad 3 \times 3$$

$\Rightarrow$

3 - 3

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad 3 \times 3$$

3 - 2

Leading principal minors are:

$$\begin{aligned}
 |A_1| &= |a_{11}| \quad \text{1st order} \\
 |A_2| &= \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} \quad \text{2nd order} \\
 |A_3| &= \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \quad \text{3rd order}
 \end{aligned}$$

For Hessian Matrix of function $y = f(x_1, x_2, \dots, x_n)$

$$H = \begin{bmatrix} f_{11} & f_{12} & f_{13} & \dots & f_{1n} \\ f_{21} & f_{22} & f_{23} & \dots & f_{2n} \\ f_{31} & f_{32} & f_{33} & \dots & f_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ f_{n1} & f_{n2} & f_{n3} & \dots & f_{nn} \end{bmatrix} \quad n \times n$$

$$H_1 = [f_{11}]$$

$$H_2 = \begin{bmatrix} f_{11} & f_{12} \\ f_{21} & f_{22} \end{bmatrix} \quad \dots \text{delete the last row \& column}$$

$$H_3 = \begin{bmatrix} f_{11} & f_{12} & f_{13} \\ f_{21} & f_{22} & f_{23} \\ f_{31} & f_{32} & f_{33} \end{bmatrix} \quad \dots \text{delete the last row \& column} \quad \dots H_n = H$$

Leading principal minors are:

$$|H_1| = |f_{11}| \quad \text{this is not the absolute sign}$$

$$|H_2| = \begin{vmatrix} f_{11} & f_{12} \\ f_{21} & f_{22} \end{vmatrix}$$

$$|H_3| = \begin{vmatrix} f_{11} & f_{12} & f_{13} \\ f_{21} & f_{22} & f_{23} \\ f_{31} & f_{32} & f_{33} \end{vmatrix} \quad \dots \quad |H_n| = |H|$$

📖 About “Definiteness of H ”

Let H be a symmetric matrix with dimension $n \times n$

$d^2z > 0$ (a) H is **positive definite** if all n leading principal minors are positive
 $|H_1| > 0, |H_2| > 0, |H_3| > 0, \dots$ all positive

$d^2z < 0$ (b) H is **negative definite** if n leading principal minor duly alternate in sign with the first one being negative.

$|H_1| < 0, |H_2| > 0, |H_3| < 0, \dots$ starting with negative, alternate in sign

If (a) or (b) is not met, H is indefinite.

Example: Find definiteness of matrix $B = \begin{bmatrix} -3 & 4 \\ 4 & -6 \end{bmatrix}_{2 \times 2}$

$B_1 = [-3], |B_1| = -3 < 0$
 $B_2 = B = \begin{bmatrix} -3 & 4 \\ 4 & -6 \end{bmatrix}, |B_2| = 18 - 16 = 2 > 0$
 B is neg. definite

Homework: Find definiteness of the following symmetric matrices ต่อไปนี้

(a) $\begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$

(e) $\begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 5 \\ 0 & 5 & 6 \end{bmatrix}$

(b) $\begin{bmatrix} -3 & 4 \\ 4 & -5 \end{bmatrix}$

(f) $\begin{bmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & -2 \end{bmatrix}$

(c) $\begin{bmatrix} -3 & 4 \\ 4 & -6 \end{bmatrix}$

(g) $\begin{bmatrix} 1 & 0 & 3 & 0 \\ 0 & 2 & 0 & 5 \\ 3 & 0 & 4 & 0 \\ 0 & 5 & 0 & 6 \end{bmatrix}$

Second-Order Sufficient Condition (SOSC, SOC)

For the maximum of objective function $z = f(x, y)$

the slope is decreasing ... $d^2z < 0$, d^2z neg def.

$\Rightarrow H$ is neg def.

$$H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$$

$$|H_1| = f_{xx} < 0$$

$$|H_2| = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} = f_{xx}f_{yy} - (f_{xy})^2 > 0$$

For the minimum of objective function $z = f(x, y)$

the slope is increasing ... $d^2z > 0$, d^2z positive def.

$\Rightarrow H$ is positive def.

$$H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$$

$$|H_1| = f_{xx} > 0$$

$$|H_2| = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} = f_{xx}f_{yy} - (f_{xy})^2 > 0$$

Example: Find the maximum/minimum of function $z = x + 2ey - e^x - e^{2y}$

$$\text{FOC: } \frac{\partial z}{\partial x} = 1 - e^x = 0 \Rightarrow x^* = 0$$

$$\frac{\partial z}{\partial y} = 2e - 2e^{2y} = 0 \Rightarrow e = e^{2y}$$

$$\text{note: } \frac{d}{dx} e^{kx} = ke^{kx} \quad 2y = 1 \Rightarrow y^* = \frac{1}{2}$$

$$\text{SOC: } f_{xx} = \frac{\partial f_x}{\partial x} = \frac{\partial (1 - e^x)}{\partial x} = -e^x$$

$$f_{xy} = f_{yx} = \frac{\partial f_x}{\partial y} = \frac{\partial (1 - e^x)}{\partial y} = 0$$

$$f_{yy} = \frac{\partial f_y}{\partial y} = \frac{\partial (2e - 2e^{2y})}{\partial y} = -4e^{2y}$$

$$H = \begin{bmatrix} -e^x & 0 \\ 0 & -4e^{2y} \end{bmatrix}$$

$$|H_1| = |-e^x| = -e^x < 0$$

$$|H_2| = 4e^{2+2y} = 4e^{0+2 \cdot \frac{1}{2}} = 4e > 0$$

H is neg def. $\therefore (x^*, y^*)$ gives $z_{\max}$

$$z_{\max} = 0 + e - 1 - e = -1 \quad \#$$



Objective functions with more three choice variables

$$z = f(x_1, x_2, x_3)$$

F.O.N.C :

$$dz = 0$$

$$dz = f_1 dx_1 + f_2 dx_2 + f_3 dx_3 = 0; dx_1, dx_2, dx_3 > 0$$

$$f_1 = f_2 = f_3 = 0$$

$$f_1 = f_2 = f_3 = \dots = f_n = 0$$

We can use $f_1 = f_2 = f_3 = 0$ to find the stationary values/critical values

S.O.S.C

$$H = \begin{bmatrix} f_{11} & f_{12} & f_{13} \\ f_{21} & f_{22} & f_{23} \\ f_{31} & f_{32} & f_{33} \end{bmatrix} \quad 3 \times 3$$

All leading principal minor

$$|H_1| = |f_{11}|$$

$$|H_2| = \begin{vmatrix} f_{11} & f_{12} \\ f_{21} & f_{22} \end{vmatrix}$$

$$|H_3| = \begin{vmatrix} f_{11} & f_{12} & f_{13} \\ f_{21} & f_{22} & f_{23} \\ f_{31} & f_{32} & f_{33} \end{vmatrix}$$

z is at the $\begin{bmatrix} \text{maximum} \\ \text{minimum} \end{bmatrix}$ if $\begin{cases} d^2 z < 0 \\ d^2 z > 0 \end{cases}$ if $\begin{cases} |H_1| < 0, |H_2| > 0, |H_3| < 0 \\ |H_1| > 0, |H_2| > 0, |H_3| > 0 \end{cases}$ if $\begin{cases} H \text{ is negative definite} \\ H \text{ is positive definite} \end{cases}$



Objective functions with more n –choice variables

$$z = f(x_1, x_2, x_3, \dots, x_n)$$

F.O.N.C :

$$dz = f_1 dx_1 + f_2 dx_2 + \dots + f_n dx_n = 0$$

$$\frac{\partial^2 f_i}{\partial x_i} = 0, \text{ for all } i, i = 1, 2, \dots, n$$

S.O.S.C:

$$\therefore |H| = \begin{vmatrix} f_{11} & f_{12} & \dots & f_{1n} \\ f_{21} & f_{22} & \dots & f_{2n} \\ \dots & \dots & \dots & \dots \\ f_{n1} & f_{n2} & \dots & f_{nn} \end{vmatrix}$$

All principal minors $|H_1|, |H_2|, \dots, |H_n|$

If z is at is the maximum when $d^2 z < 0$, H is negative definite:

$$|H_1| < 0, |H_2| > 0, |H_3| < 0, |H_4| > 0, |H_5| < 0, \dots$$

If z is at is the minimum when $d^2 z > 0$, H is positive definite:

$$|H_1| > 0, |H_2| > 0, |H_3| > 0, |H_4| > 0, |H_5| > 0, \dots$$

Homework: Find extreme values of the following functions and check for the sufficient condition

$$z = 8x^3 + 2xy - 3x^2 + y^2 + 1$$

$$z = 2x_1^2 + x_1x_2 + 4x_2^2 + x_1x_3 + x_3^2 + 2$$

$$z = -3x_1^3 + 3x_1x_3 + 2x_2 - x_2^2 - 3x_3^2$$

$$z = x_1^2 + 3x_2^2 - 3x_1x_2 + 4x_2x_3 + 6x_3^2$$

$$z = x_1x_3 + x_1^2 - x_2 + x_2x_3 + x_2^2 + 3x_3^2$$

$$z = e^x + e^y + e^{w^2} - 2e^w - (x + y)$$

$$z = x^4 + x^2 - 6xy + 3y^2$$

$$w = x^2 + 6xy + y^2 - 3yz + 4z^2 - 10x - 5y - 21z$$

$$w = (x^2 + 2y^2 + 3z^2)e^{-(x^2 + y^2 + z^2)}$$

 Summary of optimal conditions

The objective function: $z = f(x, y)$

Condition	Maximum	Minimum
First-order necessary (FONC, FOC)	$f_x = f_y = 0$	$f_x = f_y = 0$
Second-order sufficient (SOSC, SOC)	$ H_1 = f_{xx} < 0$ $ H_2 = f_{xx}f_{yy} - f_{xy}^2 > 0$	$ H_1 = f_{xx} > 0$ $ H_2 = f_{xx}f_{yy} - f_{xy}^2 > 0$

$H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{xy} & f_{yy} \end{bmatrix}$

The objective function: $z = f(x_1, x_2, \dots, x_n)$

Condition	Maximum	Minimum
First-order necessary (FONC, FOC)	$f_1 = f_2 = \dots = f_n = 0$	$f_1 = f_2 = \dots = f_n = 0$
Second-order sufficient (SOSC, SOC)	$d^2z < 0$, negative def. H is negative definite. $(-1)^k H_k > 0$ $k = 1, 2, \dots, n$	$d^2z > 0$, positive def. H is positive definite. $ H_k > 0$ $k = 1, 2, \dots, n$

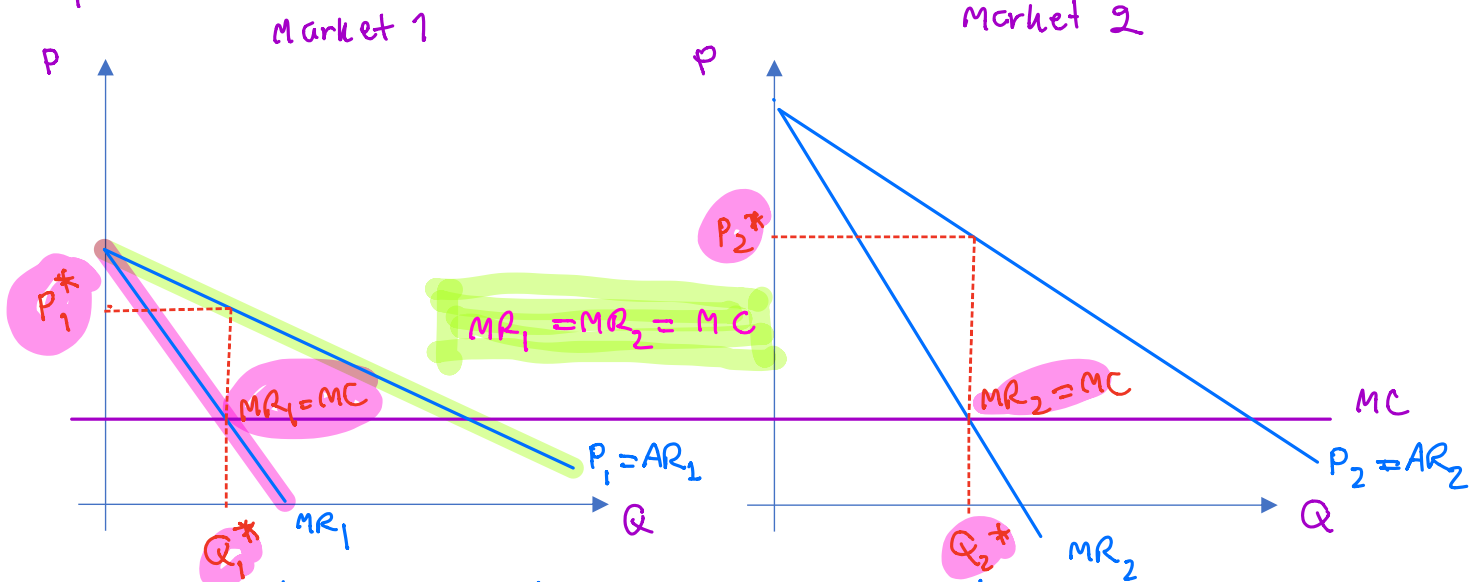
$(-1)^1 |H_1| > 0$
 $(-1)^2 |H_2| > 0$

Third-Degree Price Discrimination

Monopolist

Third-Degree Price Discrimination involves charging different prices to different segments of the market for the same good. This is to maximize profit within each segment of the market. For example, a theater may divide cinema goers into seniors, adults, and children, each paying a different price when seeing the same movie.

Example : Assume $MC = \text{constant}$



Suppose that there are three segmented markets

Total Revenue of a company is:

$$TR = R_1(Q_1) + R_2(Q_2) + R_3(Q_3),$$

R_i is a total revenue function of market i .

segment market according to the nature of consumer's demand in each market

Total cost of the company is:

$$C = C(Q)$$

$$Q = Q_1 + Q_2 + Q_3$$

total quantity produced

Q_i is quantity of product sold in market i .

Find the quantity and price in each market i that maximizes firm's profit.

Step 1 State the objective Function: Profit function

$$\pi = TR - TC$$

$$\max_{Q_1, Q_2, Q_3} \pi = R_1(Q_1) + R_2(Q_2) + R_3(Q_3) - C(Q) ; Q = Q_1 + Q_2 + Q_3$$

$$\max_{Q_1, Q_2, Q_3} \pi = R_1(Q_1) + R_2(Q_2) + R_3(Q_3) - C(Q) ; Q = Q_1 + Q_2 + Q_3$$

Step 2 Find FONC and use FONC to find critical values

FoC

$$\begin{aligned} \frac{\partial \pi}{\partial Q_1} = \pi_1 &= R_1'(Q_1) - C'(Q) \frac{\partial Q}{\partial Q_1} = 0 \quad (1) \\ \frac{\partial \pi}{\partial Q_2} = \pi_2 &= R_2'(Q_2) - C'(Q) \frac{\partial Q}{\partial Q_2} = 0 \quad (2) \\ \frac{\partial \pi}{\partial Q_3} = \pi_3 &= R_3'(Q_3) - C'(Q) \frac{\partial Q}{\partial Q_3} = 0 \quad (3) \end{aligned}$$

use these to derive Q_1^*, Q_2^*, Q_3^*
 $\downarrow \quad \downarrow \quad \downarrow$
 $P_1^* \quad P_2^* \quad P_3^*$
 (to get P^* we substitute Q^* into each segmented mkt. demand)

$$C'(Q) = R_1'(Q_1) = R_2'(Q_2) = R_3'(Q_3)$$

$$MC = MR_1 = MR_2 = MR_3$$

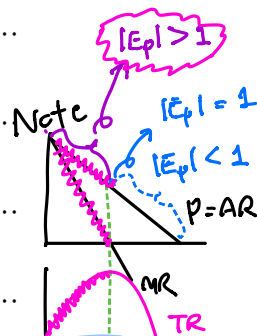
From $R_i = P_i Q_i = P_i(Q_i) Q_i$

$$MR_i = \frac{dR_i}{dQ_i} = P_i(Q_i) + Q_i \frac{dP_i(Q_i)}{dQ_i}$$

$$MR_i = P_i \left[1 + \frac{1}{E_{P_i}} \right]$$

$$MC = P_1 \left[1 + \frac{1}{E_{P_1}} \right] = P_2 \left[1 + \frac{1}{E_{P_2}} \right] = P_3 \left[1 + \frac{1}{E_{P_3}} \right]$$

more less less more



Conclusion: In the market with lower price elasticity of demand (lower $|E_{di}|$), the maximizing-profit price in that market will be more.

$$|E_P^1| < |E_P^2|$$

$$|-1.5| < |-2|$$

Step 3 Check SOSC whether $Q_1^*, P_1^*, Q_2^*, P_2^*, Q_3^*, P_3^*$ indeed give the maximum profit

Hessian Matrix:

$$H = \begin{bmatrix} \pi_{11} & \pi_{12} & \pi_{13} \\ \pi_{21} & \pi_{22} & \pi_{23} \\ \pi_{31} & \pi_{32} & \pi_{33} \end{bmatrix}$$

$$\frac{1}{E_P^1} < \frac{1}{E_P^2}$$

$$-\frac{1}{1.5} < -\frac{1}{2}$$

$$-0.67 < -0.5$$

$$1 + \frac{1}{E_P^1} < 1 + \frac{1}{E_P^2}$$

$$1 - 0.67 < 1 - 0.5$$

$$\pi_1 = MR_1 - MC, \quad \pi_{11} = MR_1 - MC \frac{\partial Q_1}{\partial Q_1} = P_1 > P_2 = 1$$

$$\pi_2 = MR_2 - MC, \quad \pi_{22} = \frac{\partial \pi_2}{\partial Q_2} = \frac{\partial (MR_2 - MC)}{\partial Q_2} = -\frac{\partial MC}{\partial Q_2} > 0$$

$$H = \begin{bmatrix} MR_1' - MC' & -MC' & -MC' \\ -MC' & MR_2' - MC' & -MC' \\ -MC' & -MC' & MR_3' - MC' \end{bmatrix}_{3 \times 3}$$

H_1 H_2 $H_3 = H$

Check all leading principal minors

H is neg def.

$$|H_1| = |\pi_{11}| = MR_1' - MC' < 0$$

$$|H_2| = \begin{vmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \end{vmatrix} = (MR_1' - MC')(MR_2' - MC') - (MC')^2 > 0$$

$$|H_3| = \begin{vmatrix} \pi_{11} & \pi_{12} & \pi_{13} \\ \pi_{21} & \pi_{22} & \pi_{23} \\ \pi_{31} & \pi_{32} & \pi_{33} \end{vmatrix} = \dots < 0$$

$\rightarrow$ at $P_1^*, Q_1^*, P_2^*, Q_2^*, P_3^*, Q_3^*$, π is maximized.

Example: Suppose a monopolist firm sells its product in three markets with corresponding market demand:

Domestic market: $P_1 = 63 - 4Q_1$

Asia market: $P_2 = 105 - 5Q_2$

Europe market: $P_3 = 75 - 6Q_3$

price = $f(Q \text{ demanded})$

Total cost function of this firm is:

$$C = 20 + 15Q;$$

$$Q = Q_1 + Q_2 + Q_3$$

Find total quantity produced by the monopolist and price and quantity in each market that maximize profit.

Step 1 State the objective Function: Profit function

$$\pi = TR - TC$$

$$= TR_1 + TR_2 + TR_3 - TC$$

$$= P_1 Q_1 + P_2 Q_2 + P_3 Q_3 - TC$$

$$\max_{Q_1, Q_2, Q_3} \pi = (63 - 4Q_1)Q_1 + (105 - 5Q_2)Q_2 + (75 - 6Q_3)Q_3 - \{20 + 15Q\}; \quad Q = Q_1 + Q_2 + Q_3$$

$$\max_{Q_1, Q_2, Q_3} \pi = (63Q_1 - 4Q_1^2) + (105Q_2 - 5Q_2^2) + (75Q_3 - 6Q_3^2) - 20 - 15Q_1 - 15Q_2 - 15Q_3$$

Step 2 Find FONC and use FONC to find critical values

$$\text{FOC : } \frac{\partial \pi}{\partial Q_1} = 63 - 8Q_1 - 15 \stackrel{\text{FOC}}{=} 0 \quad (1.) \Rightarrow Q_1^* = 6$$

$$\frac{\partial \pi}{\partial Q_2} = 105 - 10Q_2 - 15 \stackrel{\text{FOC}}{=} 0 \quad (2.) \Rightarrow Q_2^* = 9$$

$$\frac{\partial \pi}{\partial Q_3} = 75 - 12Q_3 - 15 \stackrel{\text{FOC}}{=} 0 \quad (3.) \Rightarrow Q_3^* = 5$$

$$Q = 6 + 9 + 5 = 20$$

$$p_1^* = 63 - 4(6) = 39$$

$$p_2^* = 105 - 5(9) = 60$$

$$p_3^* = 75 - 6(5) = 45$$

Step 3: SOSC

$$H = \begin{bmatrix} -8 & 0 & 0 \\ 0 & -10 & 0 \\ 0 & 0 & -12 \end{bmatrix}$$

Check all leading principal minors

$$|H_1| = |-8| = -8$$

< 0

$$|H_2| = 80$$

> 0

$$|H_3| = -8 \times -10 \times -12 = -960$$

< 0

$\therefore H$ is neg def. , Q_1^*, Q_2^*, Q_3^* maximize π
 p_1^*, p_2^*, p_3^* ∇

Competitive Firm Input Choices: Cobb-Douglas Technology

Let a firm in competitive market have Cobb-Douglas Production Function:

$$Q = L^\alpha K^\beta$$

Let wage be w , rent be r baht per unit.

Characteristics of the production function:

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Step 1 State the objective Function: Profit function

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Step 2 Find FONC and use FONC to find critical values

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[illegible]

The Economic interpretation

[illegible]

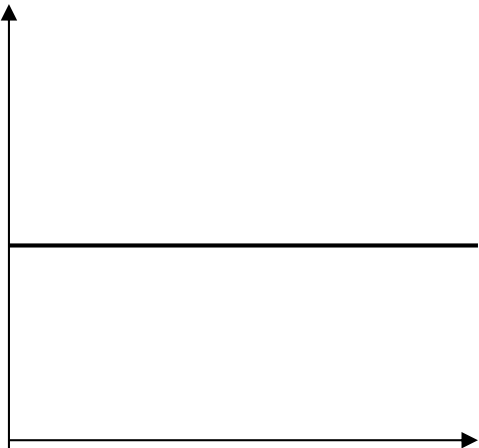
Step 3: SOSC

$$H = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

Check all leading principal minors

$|H_1| =$

$|H_2| =$





Multiproduct Firm

Multiproduct Firm in competitive market

Let a firm produce and sell two products. Each product is sold in competitive market, hence the firm is price taker. Total Revenue is:

$TR =$

- P_1 is market price of good 1.
- P_2 is market price of good 2.
- Q_1 is quantity of good 1 sold in the market.
- Q_2 is quantity of good 2 sold in the market.

Total cost of this firm is:

$C = 2Q_1^2 + Q_1Q_2 + 2Q_2^2$

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Firm’s Profit Function

$\pi = TR - TC$

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Choice Variables:

Find FONC and use FONC to find critical values

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Check Second Order Sufficient Condition (SOSC)

$H = \begin{bmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \end{bmatrix}$

$H = \begin{bmatrix} & \\ & \end{bmatrix}$

$|H_1| =$

$$|H_2| =$$

The second order differential of π , $d^2\pi$, isdefinite. Hence, the profit is.....

Multiproduct Firm in monopoly market

Let market demand of good 1 is $Q_1 = 40 - 2P_1 + P_2$

Let market demand of good 2 is $Q_2 = 15 + P_1 - P_2$

From market demand, good 1 and good 2 are

The market demands are given as functions of P_1, P_2 . Since we would like to choose Q_1, Q_2 , we need to convert the above market demands to be in the form of $P_1 = f(Q_1, Q_2)$, and $P_2 = g(Q_1, Q_2)$.

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Then, we can use the inverse market demand functions to get total revenue function:

TR =.....
.....
.....

Let the cost function of the monopolist be

$$C = 2Q_1^2 + Q_1Q_2 + 2Q_2^2$$

Profit Function:

.....
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.....

Choice Variables:

Find FONC and use FONC to find critical values

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Check Second Order Sufficient Condition (SOSC)

$$H = \begin{bmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \end{bmatrix}$$

$$H = \begin{bmatrix} & \\ & \end{bmatrix}$$

$$|H_1| =$$

$$|H_2| =$$

The second order differential of π , $d^2\pi$, isdefinite. Hence, the profit is.....

.....



Multiplant Firm Problem

Consider a firm with many plants. Each plant i has total cost TC_i .

$$TC_i = C_i(q_i), i = 1, 2, \dots, n$$

q_i is the level of output produced by factory i .

Assume that this firm sells its product in one market. Firm's total revenue function is:

$$TR = \dots\dots\dots$$

$$Q = \dots\dots\dots$$

If output market is competitive market,

.....

If output market is monopoly market,

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Firm's Profit Function

$$\pi = TR - TC$$

.....

Choice Variables:

NOTE: Third-degree price discrimination vs. Multiplant firm

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First Order Necessary Condition:

$\pi_i = \dots$ for all $i = 1, 2, \dots, n$

SOSC:

$$H = \begin{bmatrix} & \\ & \end{bmatrix}$$

$$|H_1| = R'' - C_1'' < 0$$

$$|H_2| =$$

Economic interpretation:

.....

Example: Consider a monopolist firm with two plants:

$$\text{Factory 1: } C_1(Q_1) = 10Q_1^2$$

$$\text{Factory 2: } C_2(Q_2) = 20Q_2^2$$

.....

Firm's market demand is $P = 700 - 5Q$, $Q = Q_1 + Q_2$

Draw MC_1, MC_2, MC_T, AR, MR and indicate the maximizing level of output from each plant and the profit-maximizing price.



Find Q_1 , Q_2, Q_{Total}, P that maximize profit of this firm.

Profit Function:

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Choice Variables:

Find FONC and use FONC to find critical values

This image shows a full page of white paper with horizontal dotted lines, typical of primary-ruled notebook paper. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

Check Second Order Sufficient Condition (SOSC)

$$H = \begin{bmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \end{bmatrix}$$

$$H = \begin{bmatrix} & \\ & \end{bmatrix}$$

$$|H_1| =$$

$$|H_2| =$$

The second order differential of π , $d^2\pi$, isdefinite. Hence, the profit is.....

.....

Summary:

3rd price discrimination:

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Choosing levels of factor of production:

.....

Multiproduct:

.....

Multiplant:

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