

System of Regression and Seemingly Unrelated Regression (SUR)

Chayanee Chawanote

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Outline

- System of equations: introduction and examples
- Recall GLS
- System of equations: characteristics
- Kronecker products
- Seemingly Unrelated Regression (SUR)

Introduction

- We might want to estimate a similar specification for a number of different groups
 - a cost function for each industry
- Or, we want to estimate different dependent variables for the same cross-sectional units
 - Determinants of housing expenditure, food expenditure, and clothing expenditure
- We may estimate the equations separately if the equation for a given group/a given dependent variable meets the zero conditional mean assumption
- However, we may want to estimate the equations jointly
 - to allow cross-equation restrictions to be imposed or tested
 - to gain efficiency since we might expect the error terms across equations to be contemporaneously correlated

Systems of equations

- The population model is a set of G linear equations:

$$y_1 = \mathbf{x}_1\beta_1 + u_1$$

$$y_2 = \mathbf{x}_2\beta_2 + u_2$$

$$\dots$$

$$y_G = \mathbf{x}_G\beta_G + u_G$$
 where $\mathbf{x}_g$ is $1 \times K_g$ and β_g is $K_g \times 1$, $g = 1, 2, \dots, G$
- $\mathbf{x}_g$ can be the same for all g , but the general model allows the elements and the dimension of $\mathbf{x}_g$ to vary across equations
- The system above represents a generic person, firm, city, etc. from the population, called “seemingly unrelated regressions (SUR)” model.
- In SUR model, the system has its own vector β_g , so the equations are unrelated. However, correlation across the errors in difference equations can provide links that can be exploited in estimation.
- We have independent, identically distributed cross section observations
 $\{(\mathbf{X}_i, \mathbf{y}_i) : i = 1, 2, \dots, N\}$ where $\mathbf{X}_i$ is a $G \times K$ matrix and $\mathbf{y}_i$ is a $G \times 1$ vector.
- $\mathbf{y}_i$ contains the dependent variables for all G equations.
 - $\mathbf{X}_i$ contains the explanatory variables appearing anywhere in the system.
- The multivariate linear model: $\mathbf{y}_i = \mathbf{X}_i\beta + \mathbf{u}_i$
 - β is the $K \times 1$ parameter vector and $\mathbf{u}_i$ is a $G \times 1$ vector of unobservables (errors)

Systems of equations: Characteristics

- Case 1: if $E[\mathbf{u}_i\mathbf{u}_j'] = 0$, error of equation i and j are uncorrelated. We can estimate separately or by stacking all equations together.
 - If $E[\mathbf{u}_i\mathbf{u}_i'] = \sigma_i^2 I$, OLS is BLUE
 - If $E[\mathbf{u}_i\mathbf{u}_i'] = \sigma_i^2 \Omega_i$, GLS is BLUE
- Case 2: if $E[\mathbf{u}_i\mathbf{u}_j'] \neq 0$, there is contemporaneous correlation. If not stacking them together and estimating, β_i is still consistent but not efficient.
 - $E[\mathbf{u}\mathbf{u}'] = \Sigma \otimes I_N$

Kronecker Products

- Let $A = [a_{ij}]_{m \times n}$, $B = [b_{ij}]_{p \times q}$
- $A \otimes B = \begin{bmatrix} a_{11}B & a_{12}B & \cdots & a_{1n}B \\ a_{21}B & a_{22}B & \cdots & a_{2n}B \\ \vdots & \vdots & & \vdots \\ a_{m1}B & a_{m2}B & \cdots & a_{mn}B \end{bmatrix}_{mp \times nq}$
- $(A + B) \otimes C = (A \otimes C) + (B \otimes C)$
- $(A \otimes B)(C \otimes D) = AC \otimes BD$ if AC and BD can be defined.
- $(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$ if both A and B are invertible.
- $(A \otimes B)' = A' \otimes B'$

Seemingly Unrelated Regression (SUR)

- We see that variance-covariance matrix of the error terms is not homoskedasticity, and maybe also shows contemporaneous correlation.
- The efficient way to estimate the model is to use GLS estimator.
- SUR is GLS with specific variance-covariance matrix. Find H such that $H'H = E[uu']^{-1} = \Omega^{-1}$

$$- \hat{\beta}_{GLS} = (X' * X')^{-1} X' * Y = (X' \Omega^{-1} X)^{-1} X' \Omega^{-1} Y$$

$$- \hat{\beta}_{SUR} = (X'(\Sigma \otimes I_N)^{-1} X)^{-1} X'(\Sigma \otimes I_N)^{-1} Y$$

- Theorem: $\hat{\beta}_{SUR} = \begin{bmatrix} \hat{\beta}_{1,OLS} \\ \vdots \\ \hat{\beta}_{G,OLS} \end{bmatrix}$ if

$$(1) \sigma_{ij} = 0, \forall i \neq j$$

$$(2) X_1 = X_2 = \dots = X_G = Z \text{ (All } k \text{ variables are the same)}$$

- The gain in efficiency depends on the magnitude of the cross-equation contemporaneous correlations of the residuals. The higher are those correlations, the greater the gain. Furthermore if the X_i matrices' columns are highly correlated across equations, the gains will be smaller.
- If we do not know Ω , we need a feasible SUR estimator.

- Step 1: The representative element σ_{ij} , the contemporaneous correlation between u_i and u_j , may be estimated from equation-by-equation OLS residuals
- Step 2: Calculate $\hat{\sigma}_{ij} = \frac{\hat{u}_i' \hat{u}_j}{N}$ and put into $\hat{\Sigma}$
- Step 3: Estimate by $\hat{\beta}_{FSUR} = (X'(\hat{\Sigma}^{-1} \otimes I_N)X)^{-1}X'(\hat{\Sigma}^{-1} \otimes I_N)Y$
- Step 4: Calculate $\hat{u} = Y - X\hat{\beta}_{FSUR}$
- Step 5: Use $\hat{u}$ from step 4 back to start step 2 all over again and again (iteration) until $\hat{\beta}_{FSUR}$ converges to some value of $\hat{\beta}$.